Image Alignment and Application of 2D Fast Rotational Matching in Single Particle cryo-Electron Microscopy

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cryo-EM & single particle analysis

• Single-particle electron microscopy is an excellent way to characterize the overall structure of multiprotein complexes
• Identify relative positions of individual components
• Study the dynamics of macromolecules
• With resolution still improving, single-particle analyses are already depicting secondary structures. (4-5Å)
What is Observed in Single Particle Imaging

- Single particle: particles assume random orientations in vitrified ice
- 2D views of mass density of individual proteins in random orientations
cryo-EM Micrograph of Single Particles

- electron beam is damaging to biological samples → to minimize the dose on the specimen
- the amount of signal present in any individual image is low
Classification of Images

• The primary process of single-particle analysis is the classification of images according to their Euler angles.

• Since the low SNR, the images in each classified group then being averaged to enhance the single.

• Classification methods are divided into “supervised” and “unsupervised”.

  • **Supervised:** divide according to similarity with “template” or “reference”. → homogeneous

  • **Unsupervised:** divide according to intrinsic properties. → heterogeneous

Frank et al., 1978; van Heel and Frank, 1981
2D Image Alignment Introduction

- **2D alignment**: determines the 3 relative transformation parameters of two images (1 rotat. & 2 trans.)
Model-Based refinement strategy

Classification

Class averaging

2D alignment
2D Image Alignment Introduction

- **Application:** in model-based single particle analysis

- **Classification**
- **Class averaging**
- **3D reconstruction**

- **Accuracy:** a critical factor to obtain a faithful 3D reconstruction structure

- **Efficiency:** a limiting factor for the improvement of resolution (cryo-EM, 1/4Å resolution → $10^6$ particle images)
2D Image Alignment Introduction

• Various 2D alignment methods
  
  - *direct alignment in real space*
  - *direct alignment using 2D FFT*
  - sinograms

• Commonly used 2D alignment methods:
  
  → *Resampling to Polar Coordinates (RPC)*
  
  *Polar Fourier Transform (PFT)*
  
  FFT accelerate 1D rotation search

  → *Self-Correlation Function (SCF):*
  
  SCF: inverse FT of the amplitude spectrum of the image

  SCF of an image is invariant with respect to the translation of this image

2D Image Alignment Introduction

• Current state of the art
  → **RPC/PFT** is the most accurate method.
  → **RPC/PFT** is the most efficient one if the translational search can be restricted to a small value;
    otherwise, **SCF** ranks the most efficient one.

• Classical methods describe the 3 transformation parameters of the images by 1 rota. + 2 trans. parameters fix one image & (rota. + trans.) the other

**Idea:** Rotate both objects around their own center of mass, while translate one object along the positive $x$ axis, until find the best matching position.

**FRM2D:** 2 rota.+1 trans.
- 2D FFT accelerate 2 rota. param. search
- Avoid expensive zero padding

*movie*
Resampling the objects in Polar coordinate.

The given density objects are expanded in Fourier series:

\[ f(r, \beta) = \sum_{m} \hat{f}_m(r)e^{im\beta} \]

\[ g(r, \beta) = \sum_{n} \hat{g}_n(r)e^{in\beta} \]

\( \hat{f}_m \) are the Fourier coefficients
FRM2D Description

Rotated and translated objects:

\[ f(\phi)(r, \beta) = \sum_m \hat{f}_m(r) e^{im(\beta-\phi)} \]
\[ g(\phi' ; \rho)(r, \beta) = \sum_n \hat{g}_n(r') e^{in(\beta' - \phi')} \]

The correlation function is a function of 2 rotations and 1 distance:

\[ c(\phi, \phi' ; \rho) = \int_{\mathbb{R}^2} f(\phi) \cdot g(\phi' ; \rho) \]

The criterion for matching of the two objects is to maximize the correlation between them.
FRM2D Description

Correlation function:
\[ c(\phi, \phi'; \rho) = \sum_{m,n} e^{i(m\phi+n\phi')} I_{mn}(\rho) \]

2D FT of correlation function:
\[ \hat{c}(m,n; \rho) = I_{mn}(\rho) = 2\pi \int_{0}^{\infty} (\hat{h}_{r,\rho}^n)_m \hat{f}_m(r) r \, dr \]

Inverse FFT
\[ \hat{c}(m,n; \rho) \xrightarrow{\text{Inverse FFT}} c(\phi, \phi'; \rho) \]

How can we implement the FRM2D search?

1. **Particle Image**
   - $f(r, \beta)$
   - Rotate $\phi$
   - COM, Polar Samp., FFT$_{1D}$ $\hat{f}_m(r)$

2. **Reference Image**
   - $g(r, \beta)$
   - Rotate $\phi'$
   - Translate $\rho$
   - COM, Polar Samp., FFT$_{1D}$ $\hat{g}_n(r)$

3. **Precomputing**
   - $\rho + 1$
   - $\hat{h}^n_{r,\rho}(m)$

4. **Compute Fourier Transform of Correlation**
   
   \[
   \hat{c}(m,n;\rho) = 2\pi \int_{0}^{\infty} (\hat{h}^n_{r,\rho})_m \hat{f}_m(r) r \, dr
   \]

5. **Compute Correlation**
   
   \[
   c(\phi,\phi';\rho) = \text{FFT}^{-1}_{2D}(\hat{c})
   \]

6. **For each $\rho$, update Max. Corre. value + corresp. $\phi$ and $\phi'$**

**BEST FIT**
FRM2D Accuracy and Efficiency Performance Test
Efficiency test images (RNA polymerase)

(a) reference image
104 x 104 pixels

(b) raw image
(100°; 6, -4)

SNR = $\frac{\sigma_{signal}^2}{\sigma_{noise}^2}$

SNR = 0.1477

What effects the efficiency of 2D alignment?

<table>
<thead>
<tr>
<th>Angular sampling</th>
<th>4000 particle images</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>FRM2D</td>
</tr>
<tr>
<td>K=4</td>
<td></td>
</tr>
<tr>
<td>11°</td>
<td>79.98</td>
</tr>
<tr>
<td>6°</td>
<td>174.89</td>
</tr>
<tr>
<td>3°</td>
<td>542.93</td>
</tr>
<tr>
<td>1.4°</td>
<td>2044.64</td>
</tr>
<tr>
<td>K=10</td>
<td></td>
</tr>
<tr>
<td>11°</td>
<td>104.16</td>
</tr>
<tr>
<td>6°</td>
<td>291.69</td>
</tr>
<tr>
<td>3°</td>
<td>1063.13</td>
</tr>
<tr>
<td>1.4°</td>
<td>4183.73</td>
</tr>
</tbody>
</table>

* timings in sec.

\[ l = (2k + 1)^2 \]

linear scan parameter was set to 4 or 10 pixels
Class averaging accuracy test images

Total 60,000 test particle images. SNR (0.008~153.12).

\[ SNR = \frac{\sigma_{\text{signal}}^2}{\sigma_{\text{noise}}^2} \]
Class averaging accuracy comparison

Pixel Error = \[ d \sin \left( \frac{\Delta \phi}{2} \right) + \sqrt{\Delta x^2 + \Delta y^2} \]

(a-c) Scatter plot of pixel error as a function of SNR for FRM2D, RPC and SCF
(d) Average pixel error as a function of SNR for the three methods.

- The accuracy of FRM2D and RPC is comparable especially in low SNR region.
- SCF exhibits more intrinsic sensitivity to noise than FRM2D and RPC.

### Classification accuracy test images (GroEL)

<table>
<thead>
<tr>
<th>SNR</th>
<th>Images</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.15</td>
<td><img src="image1.png" alt="Image a" /> <img src="image2.png" alt="Image b" /> <img src="image3.png" alt="Image c" /> <img src="image4.png" alt="Image d" /> <img src="image5.png" alt="Image e" /></td>
</tr>
<tr>
<td>0.06</td>
<td><img src="image1.png" alt="Image a" /> <img src="image2.png" alt="Image b" /> <img src="image3.png" alt="Image c" /> <img src="image4.png" alt="Image d" /> <img src="image5.png" alt="Image e" /></td>
</tr>
<tr>
<td>0.04</td>
<td><img src="image1.png" alt="Image a" /> <img src="image2.png" alt="Image b" /> <img src="image3.png" alt="Image c" /> <img src="image4.png" alt="Image d" /> <img src="image5.png" alt="Image e" /></td>
</tr>
<tr>
<td>0.03</td>
<td><img src="image1.png" alt="Image a" /> <img src="image2.png" alt="Image b" /> <img src="image3.png" alt="Image c" /> <img src="image4.png" alt="Image d" /> <img src="image5.png" alt="Image e" /></td>
</tr>
</tbody>
</table>

- GroEL Gaussian low-pass filtered to \(~5\text{Å}\),
- 93 projections covering all projection directions at an interval of \(4^\circ\) were generated
- random rotation, translation, flip \(\Rightarrow\) 930 test images
- \(128 \times 128\) pixels, 1.9 Å/pixel.
# Classification accuracy test

93 projections, 930 raw images

<table>
<thead>
<tr>
<th>SNR</th>
<th>Correctly classified image numbers</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>0.15</td>
</tr>
<tr>
<td>FRM2D</td>
<td>759 (82%)</td>
</tr>
<tr>
<td>SCF</td>
<td>777 (84%)</td>
</tr>
<tr>
<td>FRM2D+refine</td>
<td>892 (96%)</td>
</tr>
<tr>
<td>SCF+refine</td>
<td>872 (94%)</td>
</tr>
</tbody>
</table>

- FRM2D improves over SCF especially in cases of low SNR data (12%)
- Adding a sub-pixel refinement step is beneficial to both methods

Classification error distribution

FRM can considerably improve the classification accuracy, makes better use of available raw images
Application of FRM2D as an alignment kernel in cryo-EM 3D reconstruction
GroEL 3D reconstruction test

- 4443 raw particles, 3 data sets at different SNR level
- Initial model: X-ray structure blurred to ~30 Å
- 1.4° sampling, 5 iterations
- 0.5 FSC between the 3D reconstruction and the 5Å blurred X-ray structure

SNR = 0.15
GroEL 3D reconstructions at different noise levels

A. SNR=0.15

B. SNR=0.06

C. SNR=0.04

D.

E.

F.
Rice Dwarf Virus (RDV) 3D reconstructions

- RDV: a major pathogen of the rice plants in Southeast Asia
- Cryo-EM reconstruction: 6.8 Å with 3261 unique particles (Zhou et al. 2001)
- X-ray structure: 3.5 Å resolution (Nakagawa et al., 2003)

- RDV raw images from close-to-focus micrographs
- Collected in a JEOL 4000 electron cryomicroscopy
- Image size is 300×300 pixels with 2.8 Å/pixel
- a data set containing 3500 close-to-focus particles used in the test
- other than the 2D alignment function, all the other functions and conditions are the same
- 1.4° sampling
RDV 3D reconstruction resolution evaluations

FRM2D+refine vs. 6.8Å map

SCF+refine vs. 6.8Å map

RDV 3D reconstruction validation

(A) FRM2D \((2.4\sigma)\)

(B) SCF

(C-D) Asymmetric unit

(E) X-ray model \(\sim 8.4\ \text{Å}\)

(F) 6.8 Å model (Zhou)

\(T=13/\) icosahedral lattice
RDV 3D reconstruction validation

- The outlines of helical regions can still be recognized down to 1/7 to 1/10 Å⁻¹
- Effective resolution of FRM2D reconstruction is below 10 Å
- Utilizing FRM2D alignment kernel can accomplish reliable 3D reconstructions directly from extremely noisy experimental data sets
Summarization

- **Advantage**: using 2D FFT to accelerate the two rotational parameters search, avoiding the costly zero padding.

- **Accuracy**: FRM2D accuracy comparable to RPC, and outperforms SCF especially in low SNR cases.

- **Efficiency**: FRM2D has the potential to outperform the traditional 2D alignment methods depending on the desired fineness of angular sampling and exhaustive search range.

- **3D reconstruction**: FRM2D is a reliable and robust alignment kernel with observable resolution improvement than the classical method especially in low SNR cases.
Future directions

- Better way to determine the COM to reduce the x-axis direction scan range.
- Better way of sampling
  - Release soon with Situs and EMAN
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