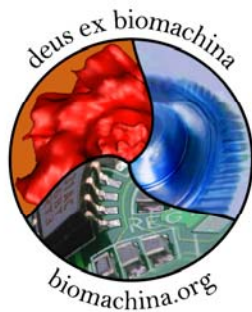


Image Alignment and Application of 2D Fast Rotational Matching in Single Particle cryo-Electron Microscopy

Yao Cong

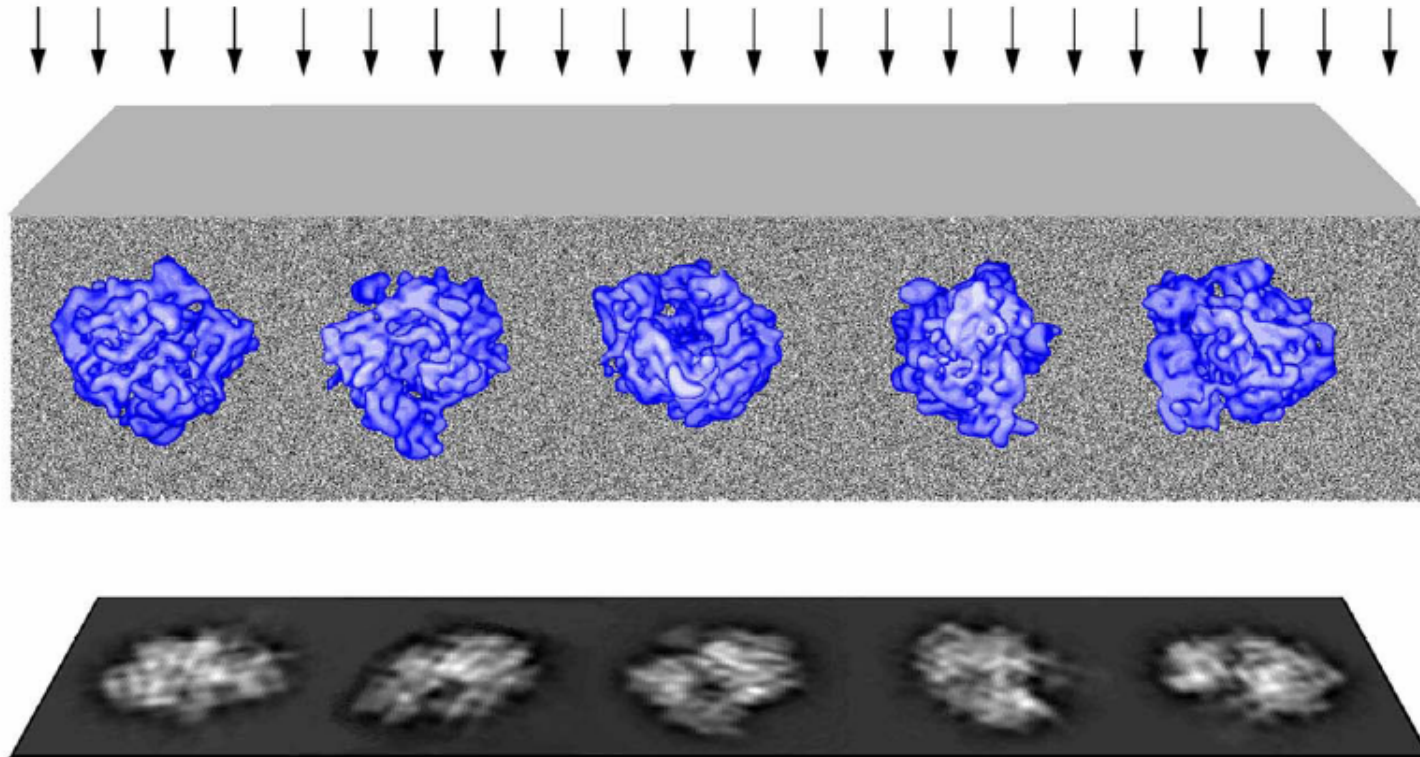
Baylor College of Medicine



cryo-EM & single particle analysis

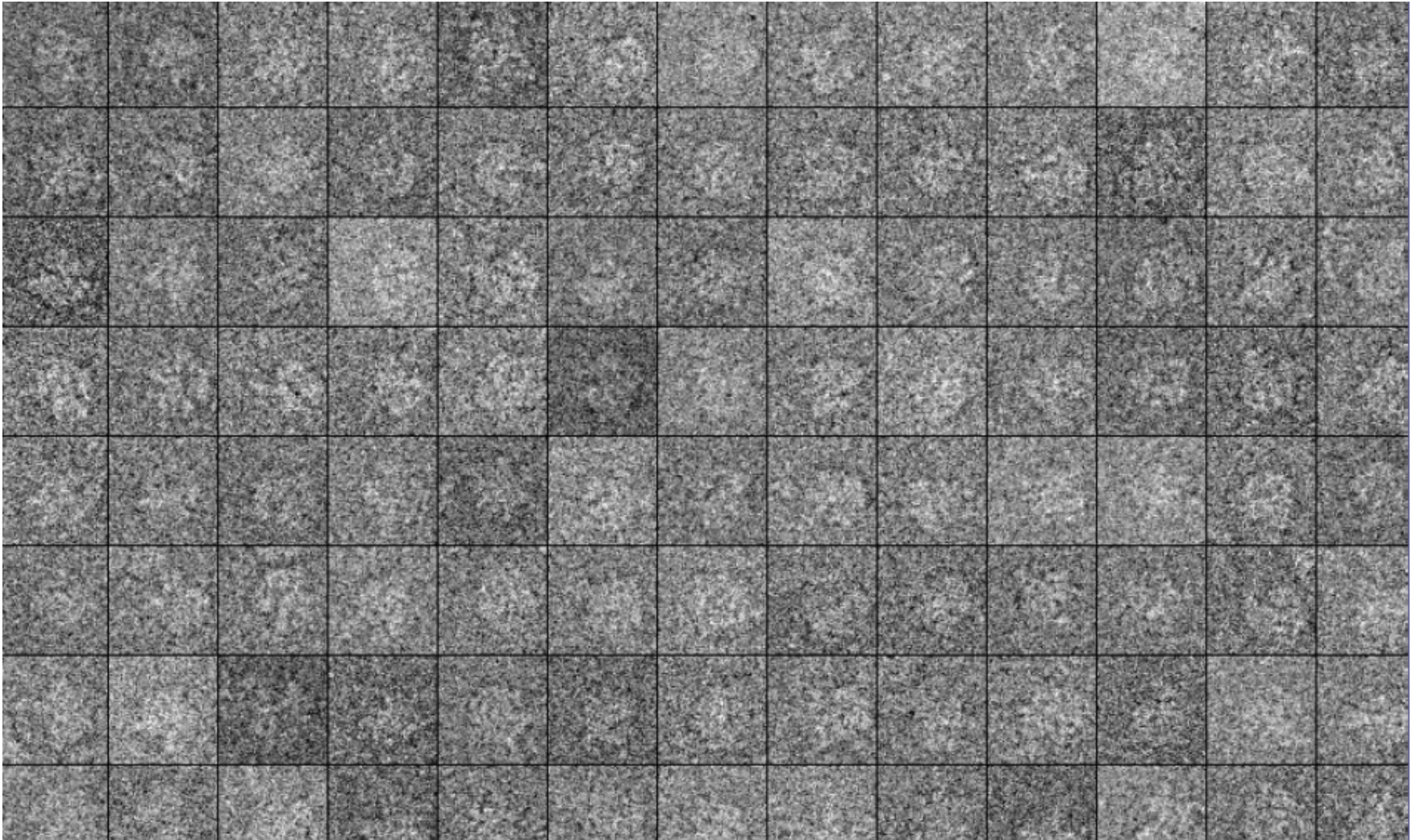
- Single-particle electron microscopy is an excellent way to characterize the overall structure of multiprotein complexes
- Identify relative positions of individual components
- Study the dynamics of macromolecules
- With resolution still improving, single-particle analyses are already depicting secondary structures. (4-5Å)

What is Observed in Single Particle Imaging



- Single particle: particles assume random orientations in vitrified ice
- 2D views of mass density of individual proteins in random orientations

cryo -EM Micrograph of Single Particles



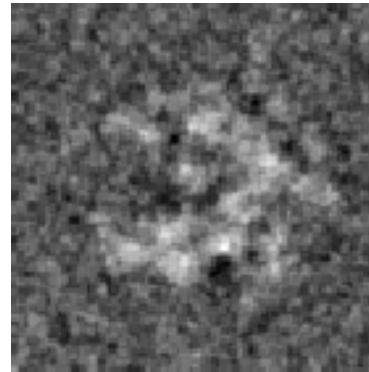
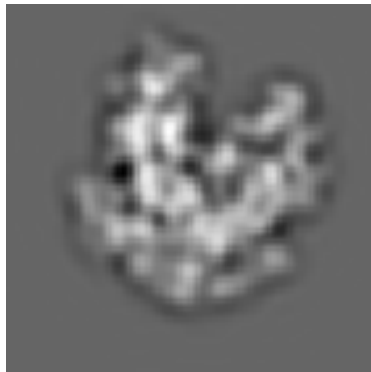
electron beam is damaging to biological samples → to minimize the dose on the specimen
→ the amount of signal present in any individual image is low

Classification of Images

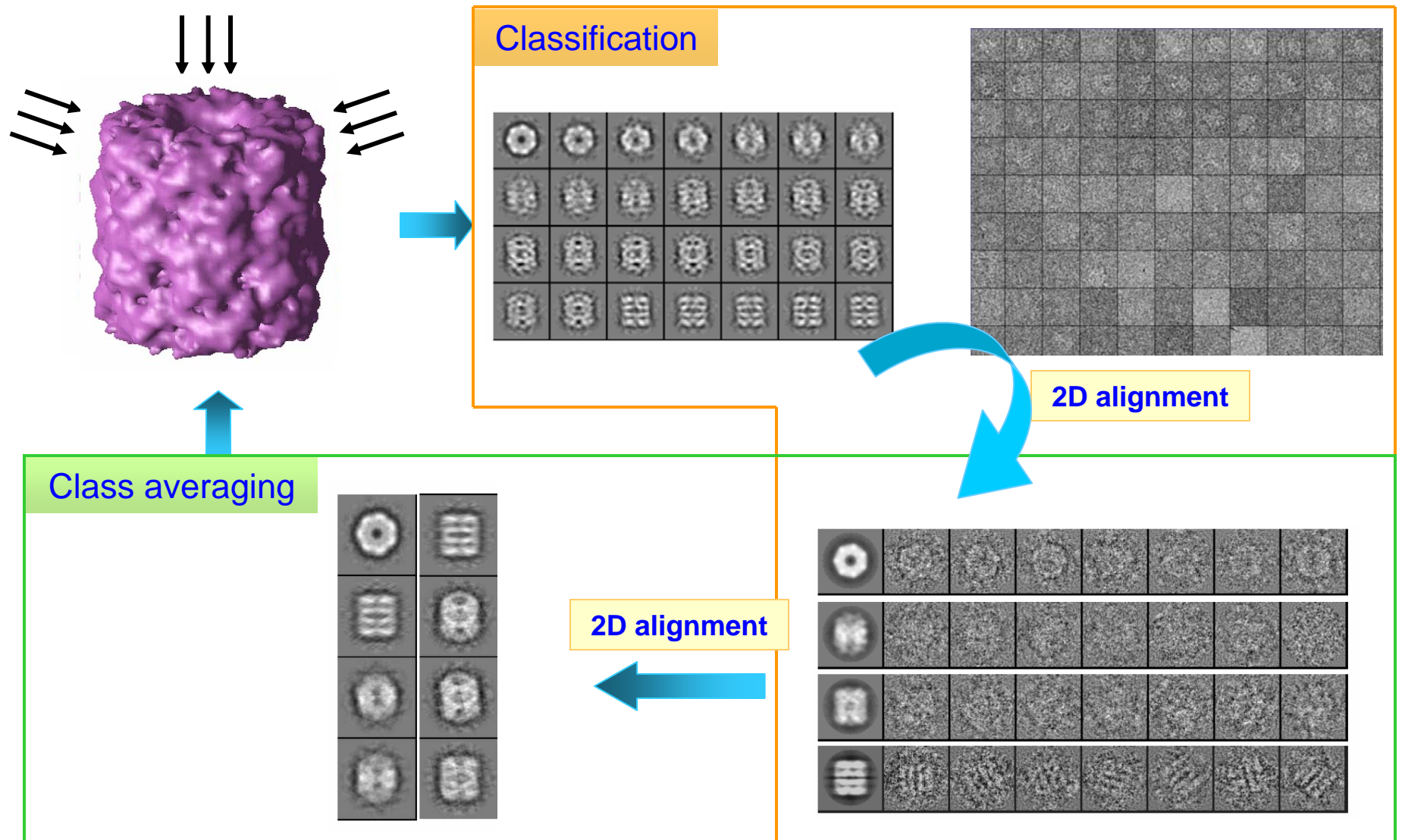
- The primary process of single-particle analysis is the classification of images according to their Euler angles
- Since the low SNR, the images in each classified group then being averaged to enhance the single
- Classification methods are divided into “supervised” and “unsupervised”
- **Supervised:** divide according to similarity with “template” or “reference”. → homogeneous
- **Unsupervised:** divide according to intrinsic properties. → heterogeneous

2D Image Alignment Introduction

- **2D alignment:** determines the 3 relative transformation parameters of two images (1 rotat. & 2 trans.)



Model-Based refinement strategy



2D Image Alignment Introduction

- **Application:** in model-based single particle analysis

- *Classification*

- *Class averaging*

- *3D reconstruction*

- **Accuracy:** a critical factor to obtain a faithful 3D reconstruction structure
- **Efficiency:** a limiting factor for the improvement of resolution (cryo-EM, 1/4Å resolution → 10⁶ particle images)

2D Image Alignment Introduction

- Various 2D alignment methods

direct alignment in real space
direct alignment using 2D FFT
sinograms

- Commonly used 2D alignment methods:

→ *Resampling to Polar Coordinates (RPC)*

Polar Fourier Transform (PFT)

FFT accelerate 1D rotation search

→ *Self-Correlation Function (SCF):*

SCF: inverse FT of the amplitude spectrum of the image

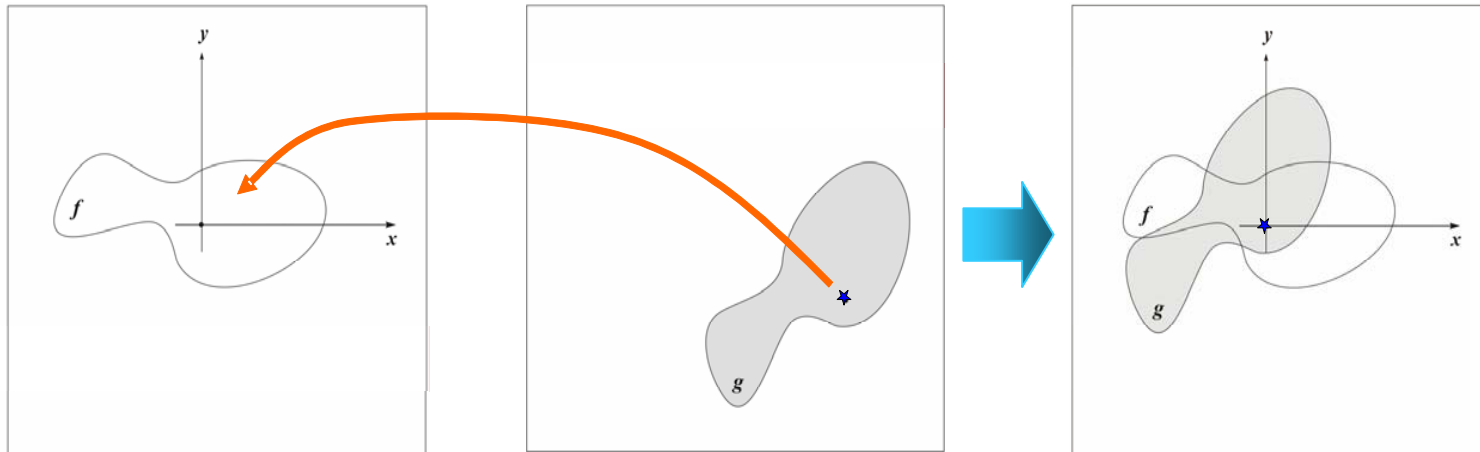
SCF of an image is invariant with respect to the translation of this image

2D Image Alignment Introduction

- Current state of the art
 - **RPC/PFT** is the most accurate method.
 - **RPC/PFT** is the most efficient one if the translational search can be restricted to a small value;
otherwise, **SCF** ranks the most efficient one.
- Classical methods describe the 3 transformation parameters of the images by **1 rota. + 2 trans.** parameters → fix one image & (rota. + trans.) the other

FRM2D Description

Idea: Rotate both objects around their own center of mass, while translate one object along the positive x axis, until find the best matching position.



FRM2D: 2 rota.+1 trans.

- 2D FFT accelerate 2 rota. param. search
- Avoid expensive zero padding

[movie](#)

FRM2D Description

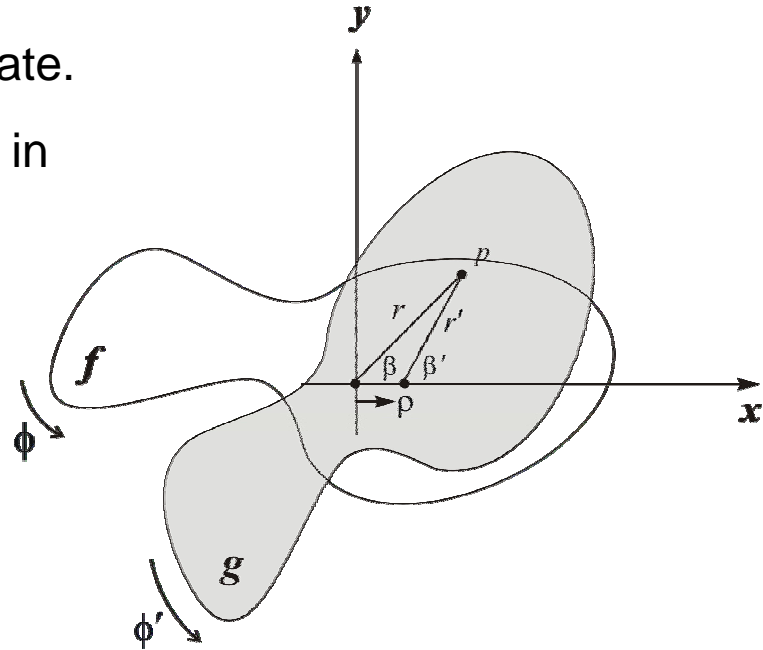
Resampling the objects in Polar coordinate.

The given density objects are expanded in Fourier series:

$$f(r, \beta) = \sum_m \hat{f}_m(r) e^{im\beta}$$

$$g(r, \beta) = \sum_n \hat{g}_n(r) e^{in\beta}$$

\hat{f}_m are the Fourier coefficients



FRM2D Description

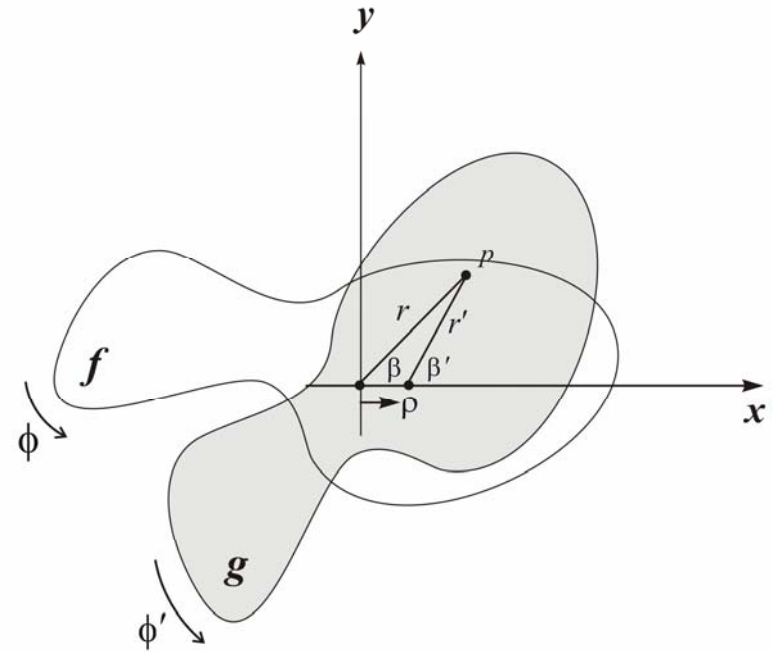
Rotated and translated objects:

$$f(\phi)(r, \beta) = \sum_m \hat{f}_m(r) e^{im(\beta - \phi)}$$

$$g(\phi'; \rho)(r, \beta) = \sum_n \hat{g}_n(r') e^{in(\beta' - \phi')}$$

The **correlation function** is a function of 2 rotations and 1 distance:

$$c(\phi, \phi'; \rho) = \int_{\mathbf{R}^2} f(\phi) \cdot g(\phi'; \rho)$$



The criterion for matching of the two objects is to **maximize** the correlation between them.

FRM2D Description

Correlation function:

$$c(\phi, \phi'; \rho) = \sum_{m,n} e^{i(m\phi+n\phi')} I_{mn}(\rho)$$

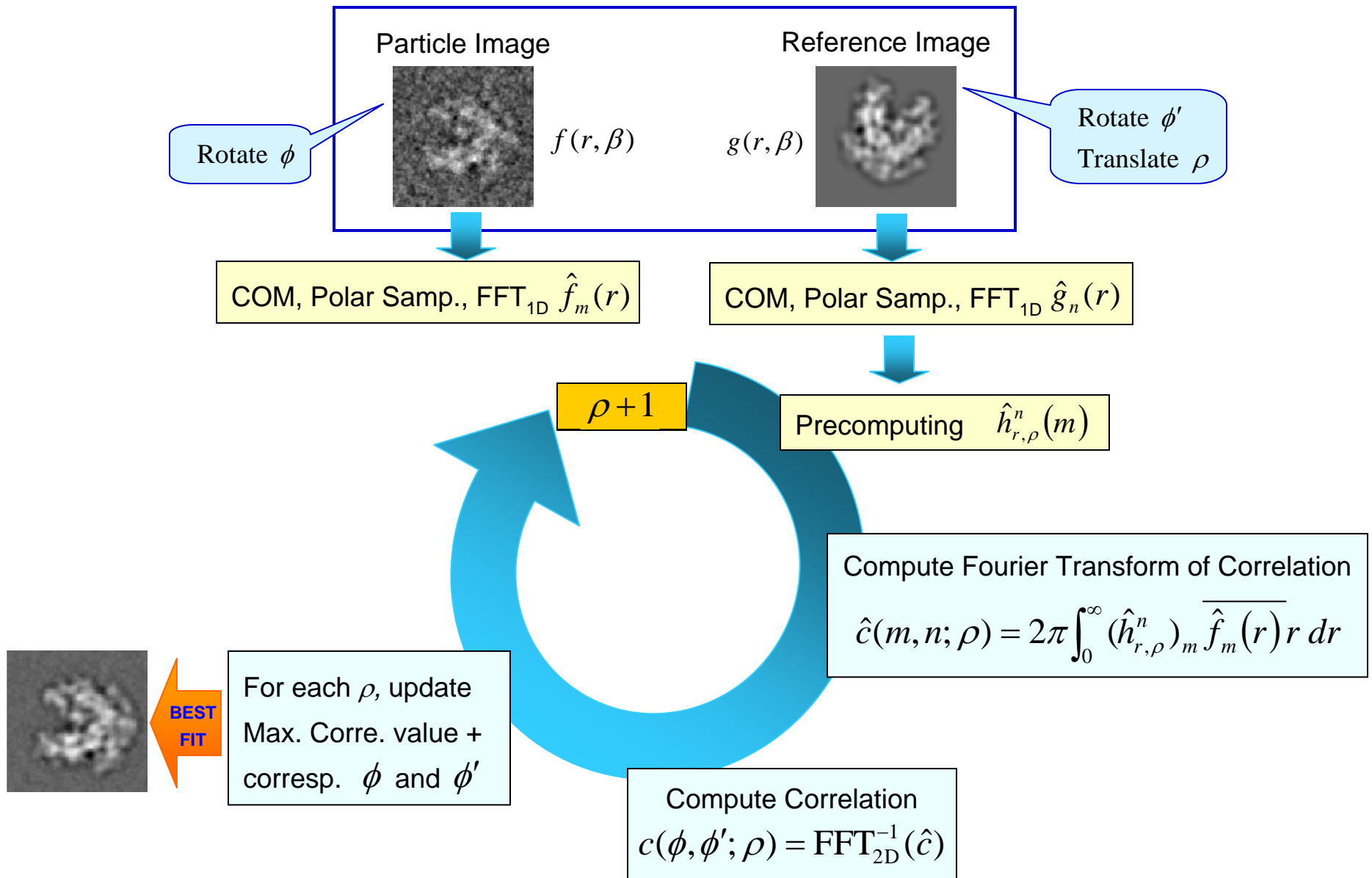


2D FT of correlation function:

$$\hat{c}(m, n; \rho) = I_{mn}(\rho) = 2\pi \int_0^\infty (\hat{h}_{r,\rho}^n)_m \overline{\hat{f}_m(r)} r dr$$

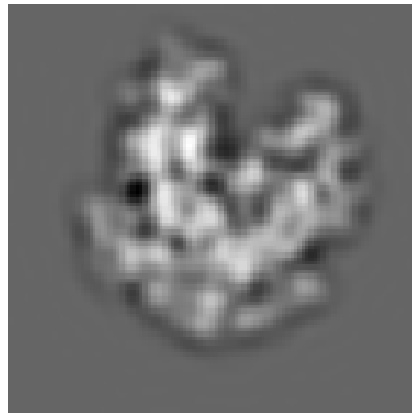
$$\hat{c}(m, n; \rho) \xrightarrow{\text{Inverse FFT}} c(\phi, \phi'; \rho)$$

How can we implement the FRM2D search?

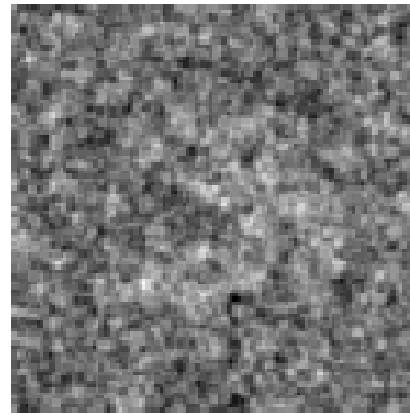


FRM2D Accuracy and Efficiency Performance Test

Efficiency test images (RNA polymerase)



(a) reference image
104 x 104 pixels



(b) raw image
(100°; 6, -4)

SNR=0.1477

$$SNR = \frac{\sigma_{signal}^2}{\sigma_{noise}^2}$$

What effects the efficiency of 2D alignment?

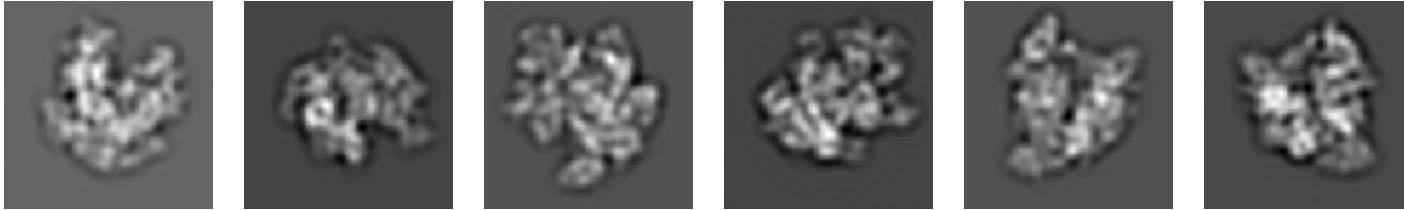
	Angular sampling	4000 particle images		
		FRM2D	RPC	SCF
K=4	11°	79.98	447.02	193.39
	6°	174.89	736.52	201.19
	3°	542.93	1552.72	214.87
	1.4°	2044.64	2875.23	238.34
K=10	11°	104.16	1958.55	193.39
	6°	291.69	3253.71	201.19
	3°	1063.13	6708.58	214.87
	1.4°	4183.73	13694.25	238.34

* timings in sec.

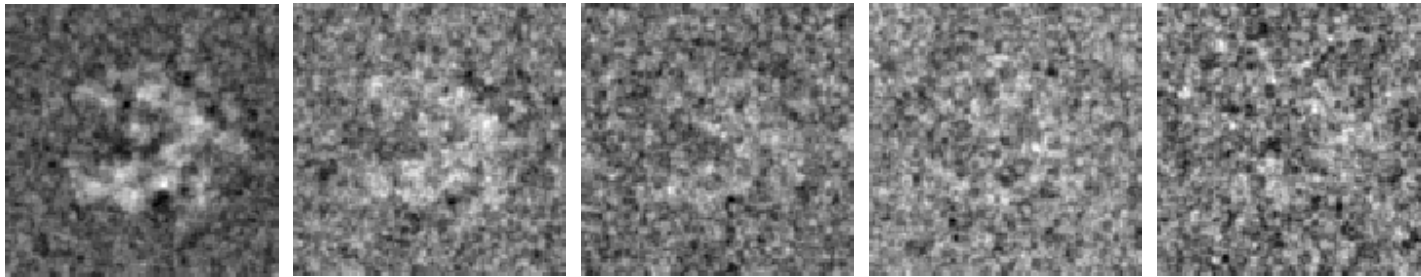
$$l = (2k + 1)^2$$

linear scan parameter was set to 4 or 10 pixels

Class averaging accuracy test images



(a)



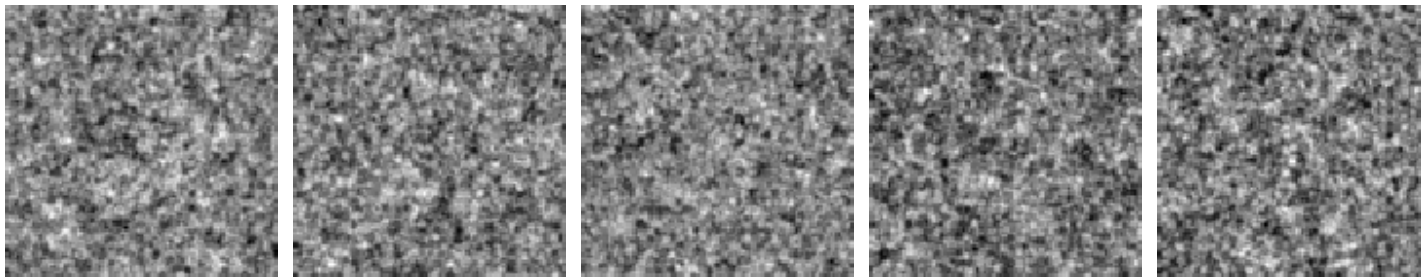
(g) (SNR=1.3716)

(h) (SNR=0.3350)

(i) (SNR=0.1477)

(j) (SNR=0.0847)

(k) (SNR=0.0544)



(l) (SNR=0.0373)

(m) (SNR=0.0282)

(n) (SNR=0.0216)

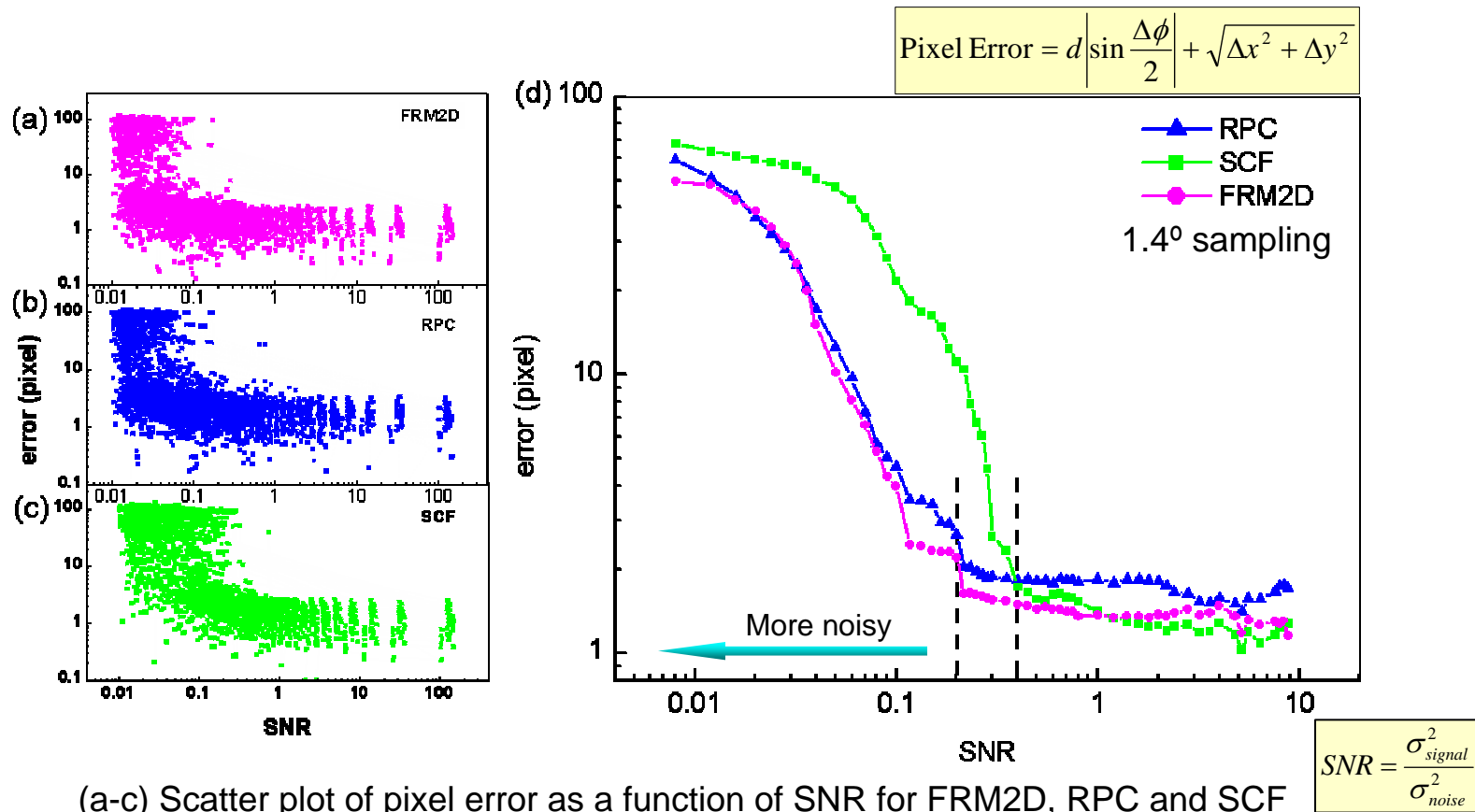
(o) (SNR=0.0173)

(p) (SNR=0.0138)

Total 60,000 test particle images. SNR (0.008~153.12).

$$SNR = \frac{\sigma_{signal}^2}{\sigma_{noise}^2}$$

Class averaging accuracy comparison

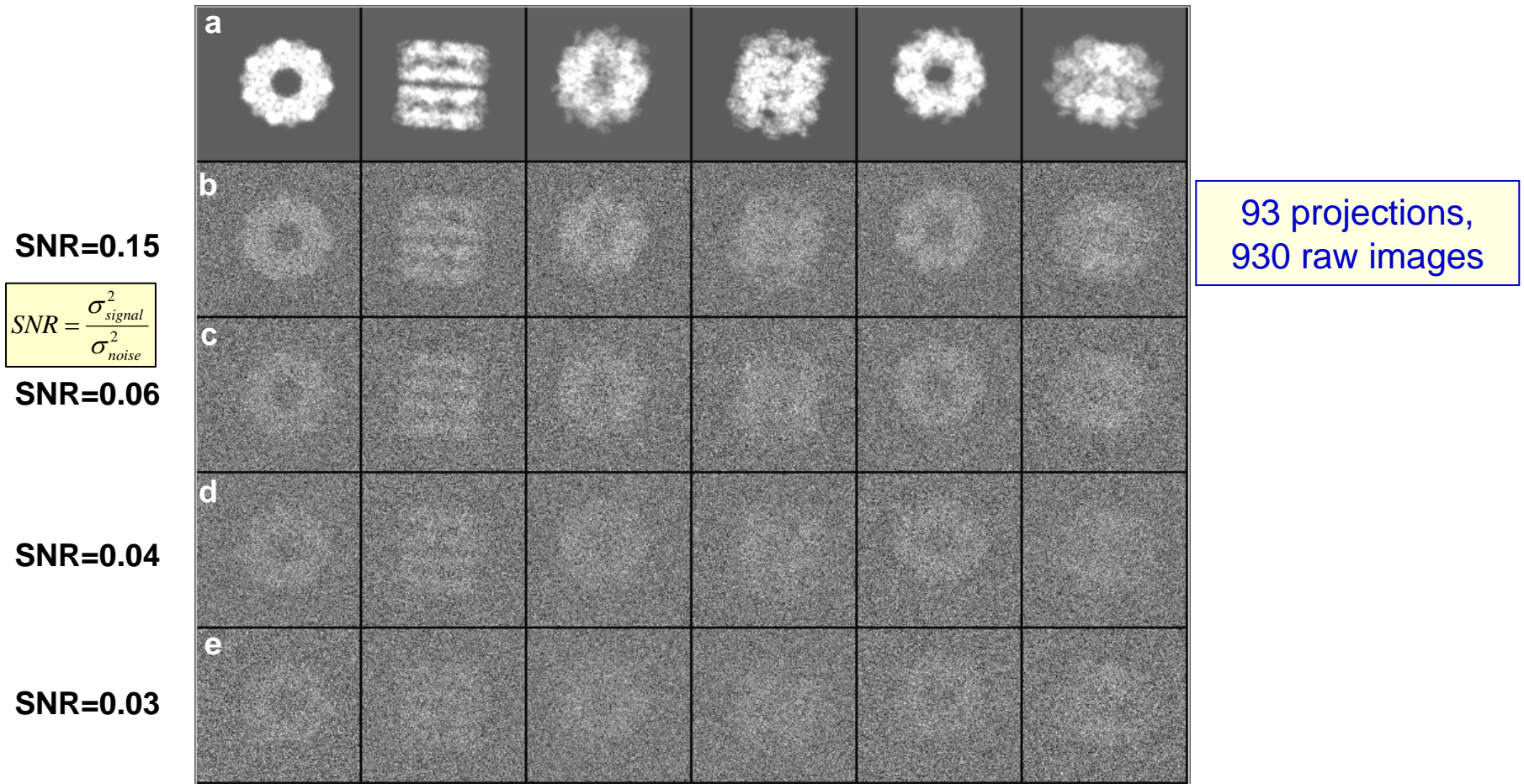


(a-c) Scatter plot of pixel error as a function of SNR for FRM2D, RPC and SCF

(d) Average pixel error as a function of SNR for the three methods.

- The accuracy of FRM2D and RPC is comparable especially in low SNR region.
- SCF exhibits more intrinsic sensitivity to noise than FRM2D and RPC.

Classification accuracy test images (GroEL)



- GroEL Gaussian low-pass filtered to $\sim 5\text{\AA}$,
- 93 projections covering all projection directions at an interval of 4° were generated
- random rotation, translation, flip \rightarrow 930 test images
- 128×128 pixels, $1.9 \text{\AA}/\text{pixel}$.

Classification accuracy test

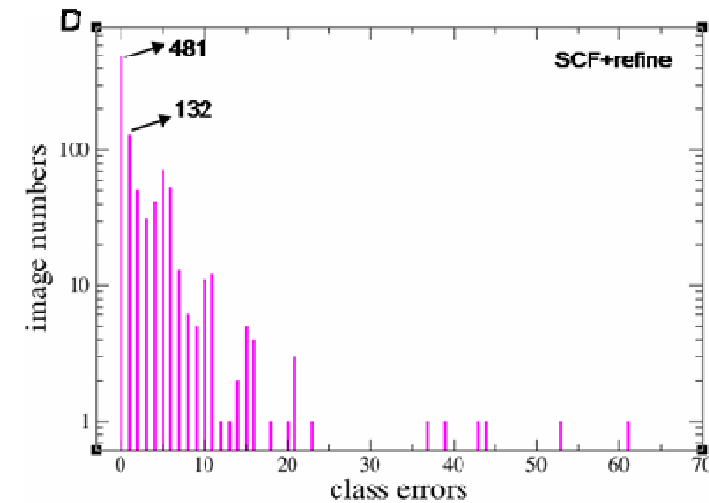
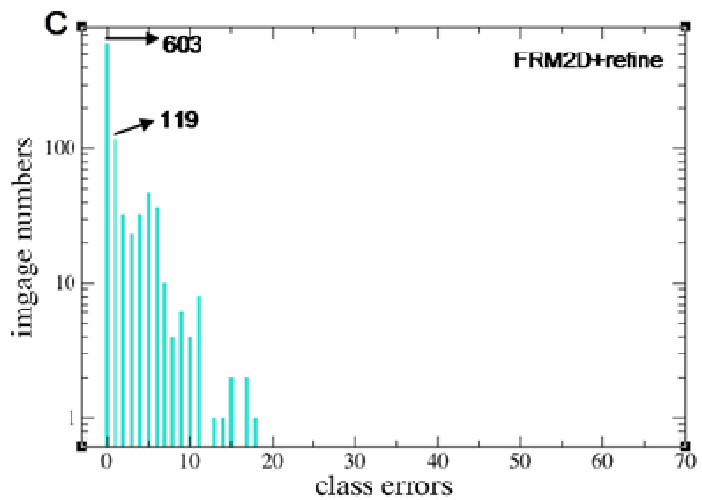
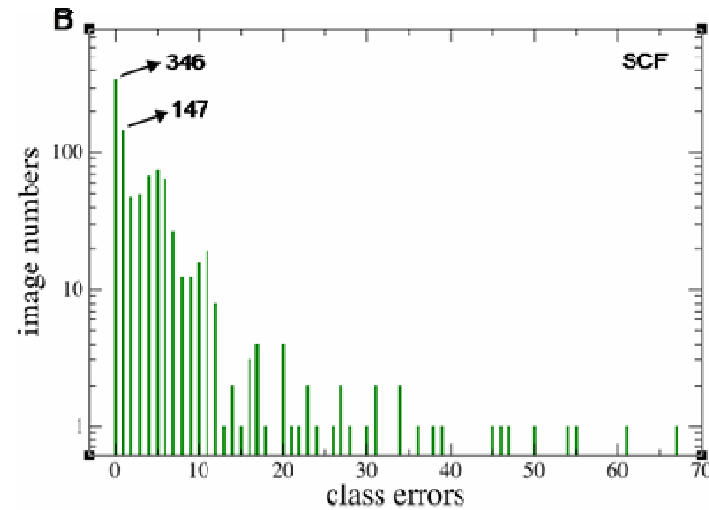
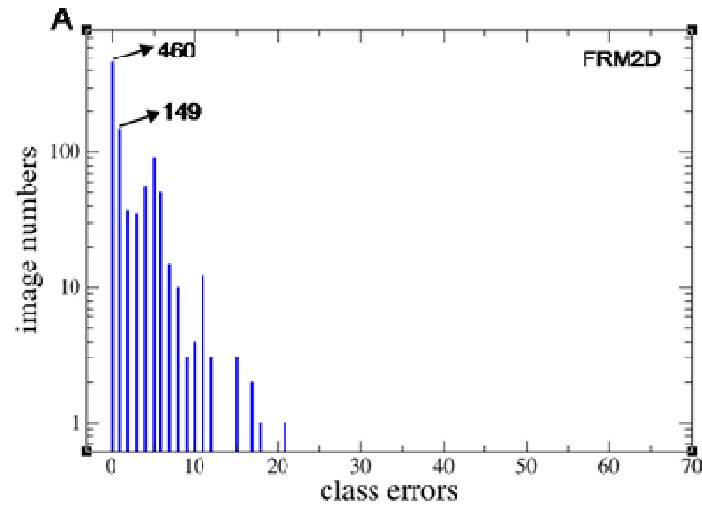
93 projections,
930 raw images

SNR	Correctly classified image numbers			
	0.15	0.06	0.04	0.03
FRM2D	759 (82%)	646 (69%)	536 (58%)	460 (49%)
SCF	777 (84%)	570 (61%)	455 (49%)	346 (37%)
FRM2D+refine	892 (96%)	768 (83%)	696 (75%)	603 (65%)
SCF+refine	872 (94%)	742 (80%)	626 (67%)	481 (52%)

- FRM2D improves over SCF especially in cases of low SNR data (12%)
- Adding a sub-pixel refinement step is beneficial to both methods

Classification error distribution

SNR=0.03

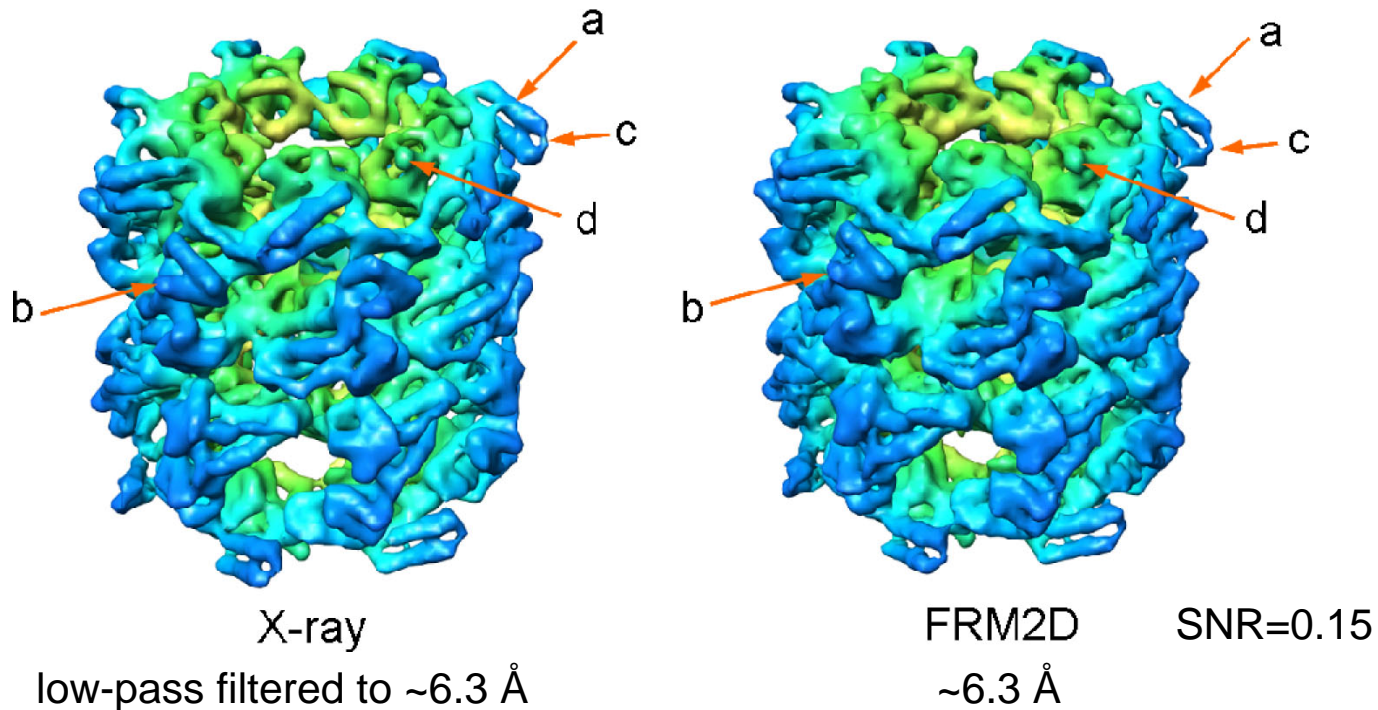


FRM can considerably improve the classification accuracy, makes better use of available raw images

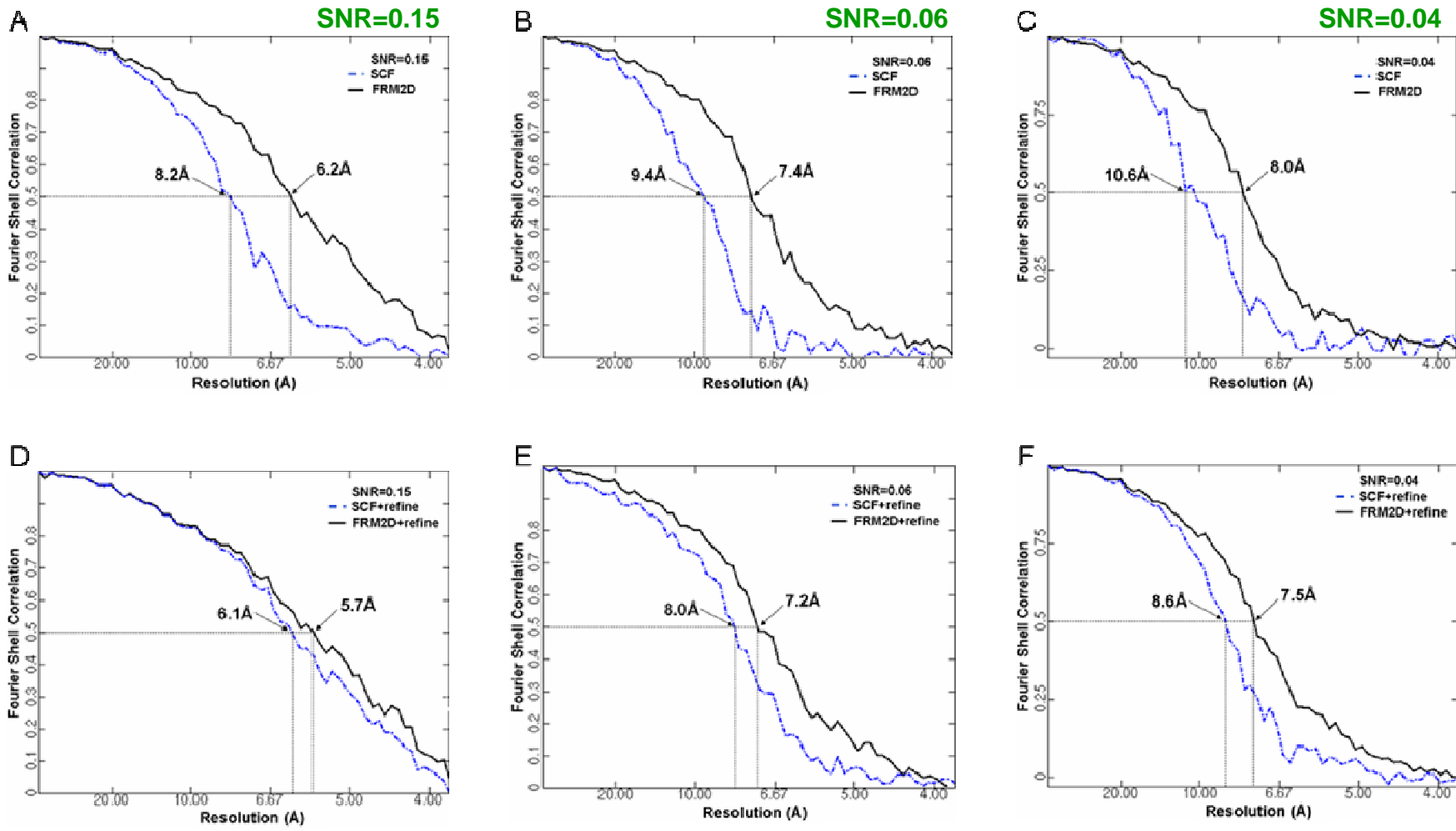
Application of FRM2D as an alignment kernel in cryo-EM 3D reconstruction

GroEL 3D reconstruction test

- 4443 raw particles, 3 date sets at different SNR level
- initial model: X-ray structure blurred to $\sim 30 \text{ \AA}$
- 1.4° sampling, 5 iterations
- 0.5 FSC between the 3D reconstruction and the 5A blurred X-ray structure

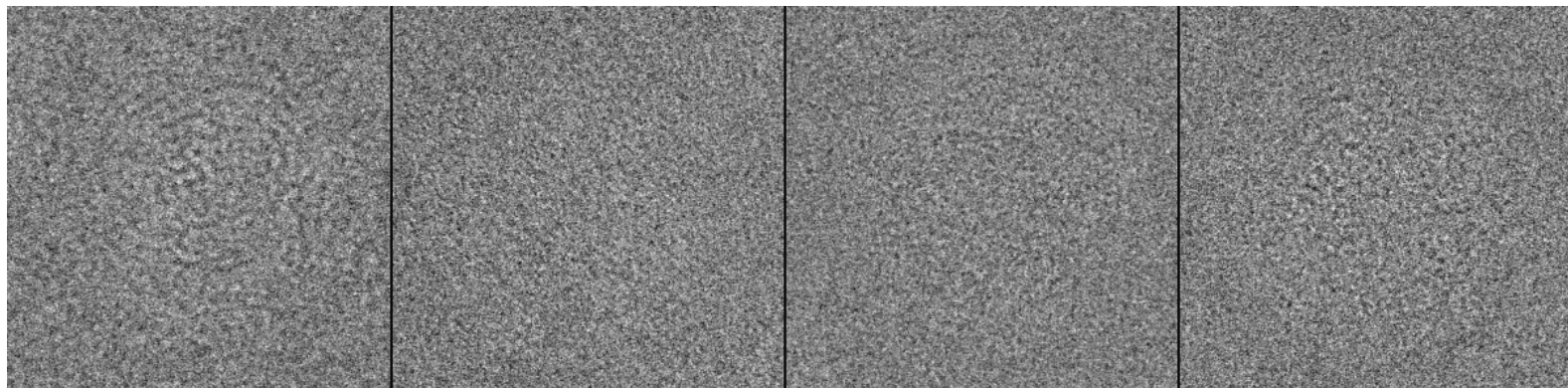


GroEL 3D reconstructions at different noise levels



Rice Dwarf Virus (RDV) 3D reconstructions

- RDV: a major pathogen of the rice plants in Southeast Asia
- Cryo-EM reconstruction: 6.8 Å with 3261 unique particles (Zhou et al. 2001)
- X-ray structure: 3.5 Å resolution (Nakagawa et al., 2003)

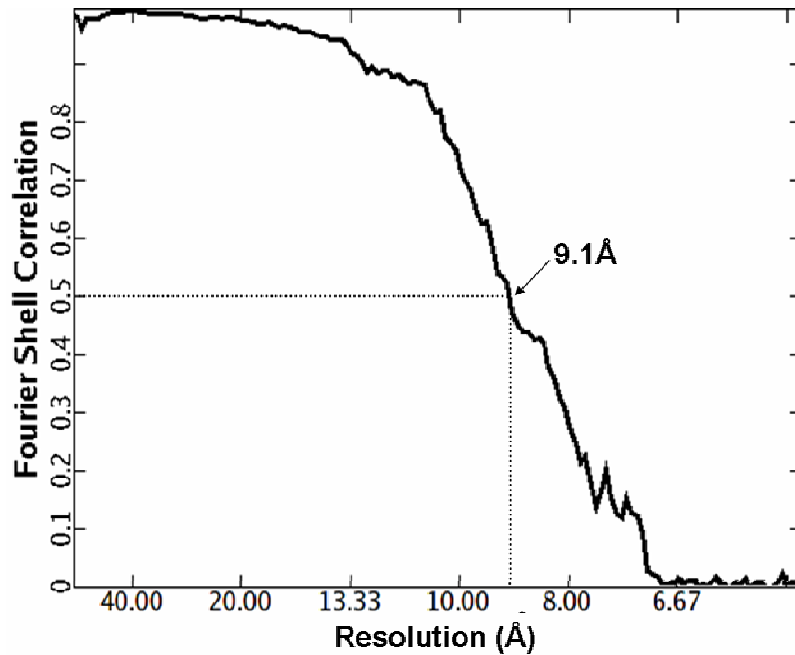


- RDV raw images from close-to-focus micrographs
- Collected in a JEOL 4000 electron cryomicroscopy
- Image size is 300×300 pixels with 2.8 Å /pixel
- a data set containing 3500 close-to-focus particles used in the test
- other than the 2D alignment function, all the other functions and conditions are the same
- 1.4° sampling

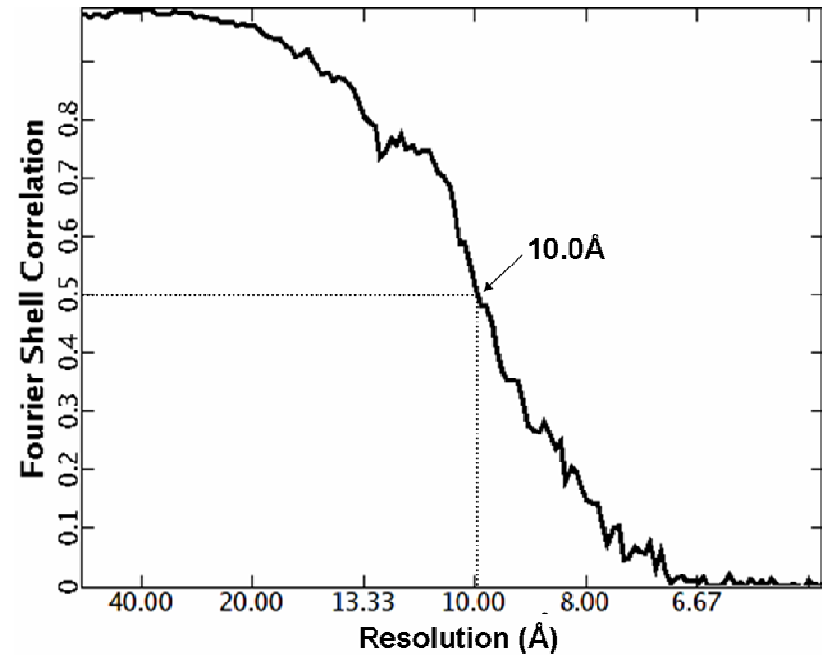
RDV 3D reconstruction resolution evaluations

1.4° sampling

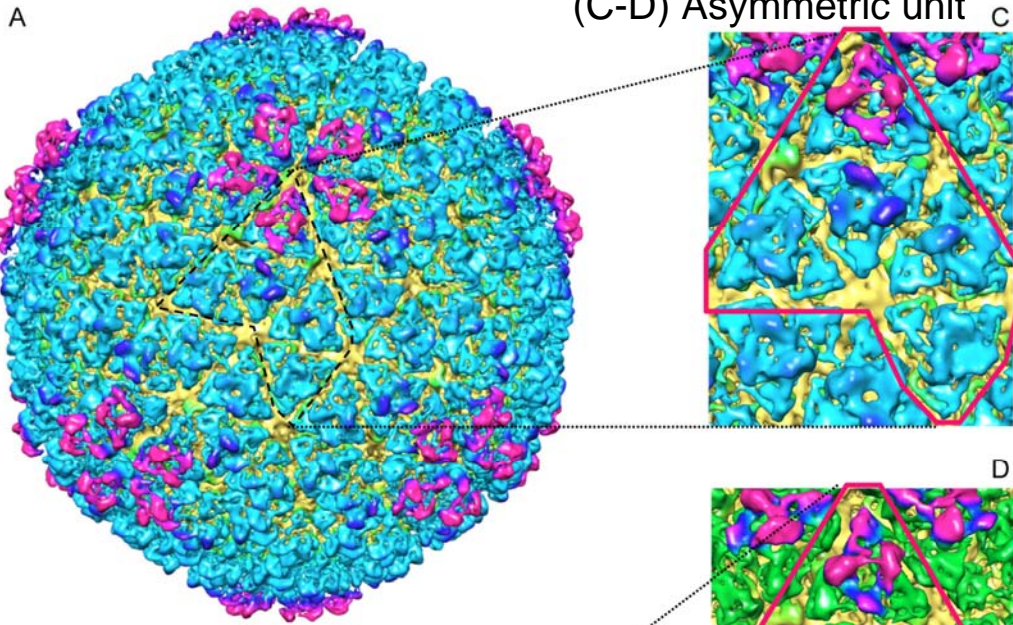
FRM2D+refine vs. 6.8Å map



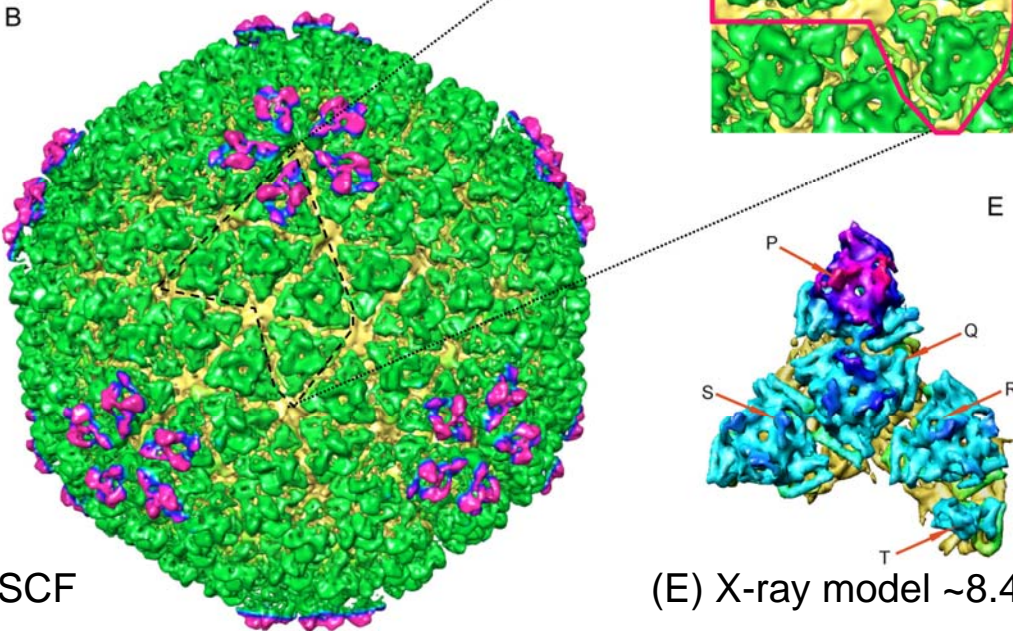
SCF+refine vs. 6.8Å map



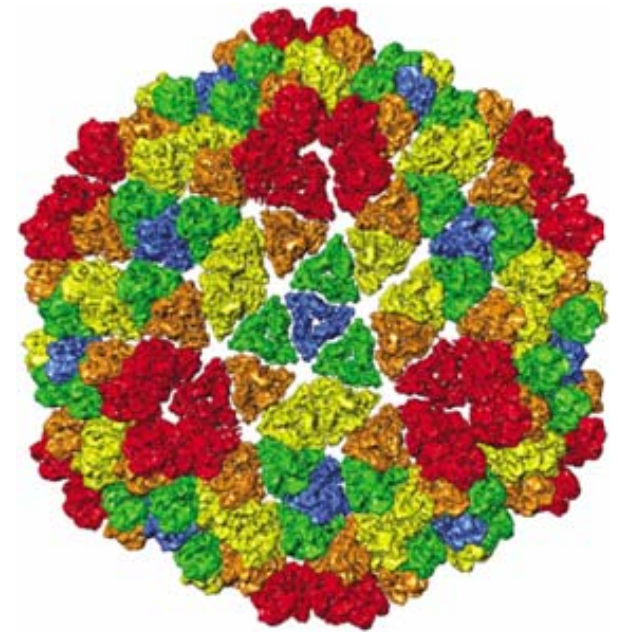
RDV 3D reconstruction validation



(A) FRM2D (2.4σ)



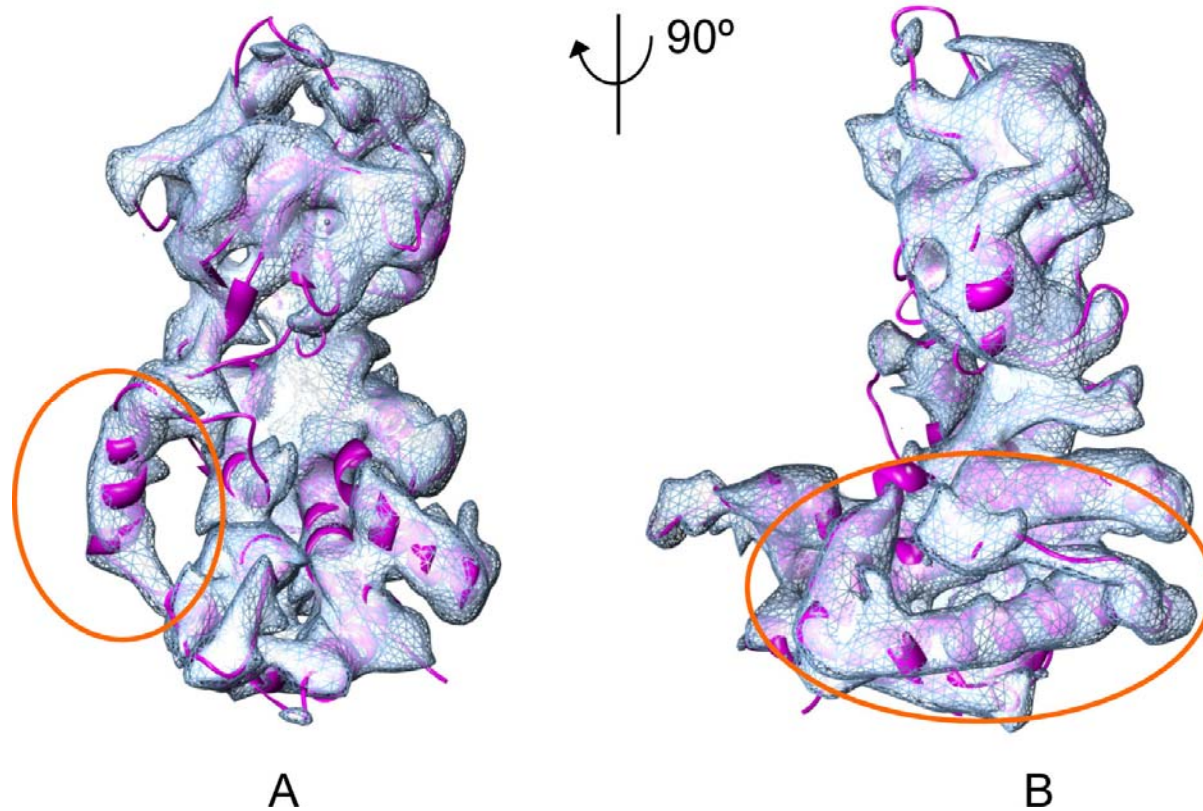
(B) SCF



(F) 6.8 Å model (Zhou)

T=13/icosahedral lattice

RDV 3D reconstruction validation



- The outlines of helical regions can still be recognized down to $1/7$ to $1/10 \text{ \AA}^{-1}$
- Effective resolution of FRM2D reconstruction is below 10 \AA
- Utilizing FRM2D alignment kernel can accomplish reliable 3D reconstructions directly from extremely noisy experimental data sets

Summarization

- Advantage: using 2D FFT to accelerate the two rotational parameters search, avoiding the costly zero padding
- Accuracy: FRM2D accuracy comparable to RPC, and outperforms SCF especially in low SNR cases.
- Efficiency: FRM2D has the potential to outperform the traditional 2D alignment methods depending on the desired fineness of angular sampling and exhaustive search range.
- 3D reconstruction: FRM2D is a reliable and robust alignment kernel with observable resolution improvement than the classical method especially in low SNR cases.

Future directions

- Better way to determine the COM to reduce the x-axis direction scan range.
- Better way of sampling
- [Release soon with Situs and EMAN](#)

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