

High Performance Computing and Visualization at the School of Health Information Sciences

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Outline

- High Performance Computing
 - Supercomputer Architectures
 - SHIS Cluster Computer System
 - Applications
- Virtual Reality
 - Virtual Reality / Haptic Rendering
 - SHIS VR system
 - SenSitus

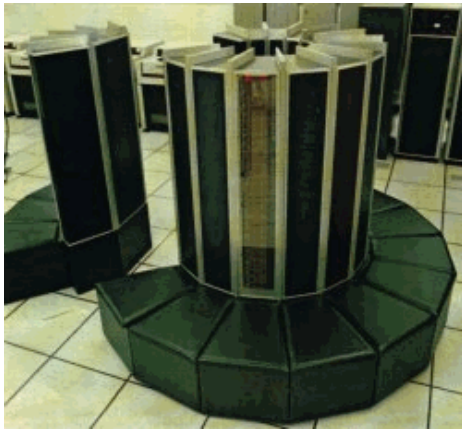


High Performance Computing

- Definition of “Supercomputer”, HPC?
 - *Computational facilities substantially more powerful than current desktop computers*
- *Performance*
 - *Flop is a floating point operation per second*
 - *Clock speed*
 - *Peak performance = Maximal calculation speed of CPU*
 - *Actual performance depends on application, memory bandwidth, interconnection network, etc.*
- *Parallelism*
 - *Multiple calculation units within a CPU, multiple CPUs, etc.*
 - *Locality of problem*



High Performance Computing



Cray 1 (1976)



Cray T3E (1995)



System X (2001)



Earth Simulator (2002)

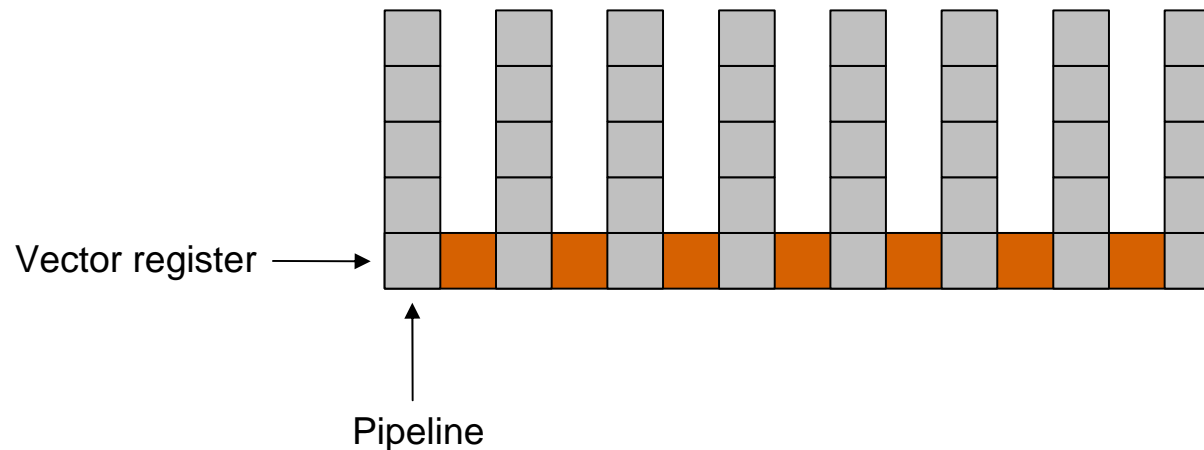


Blue Gene (2004)



Vectorcomputer

- SIMD parallelism
 - Bandwidth between memory and CPU dramatically increased

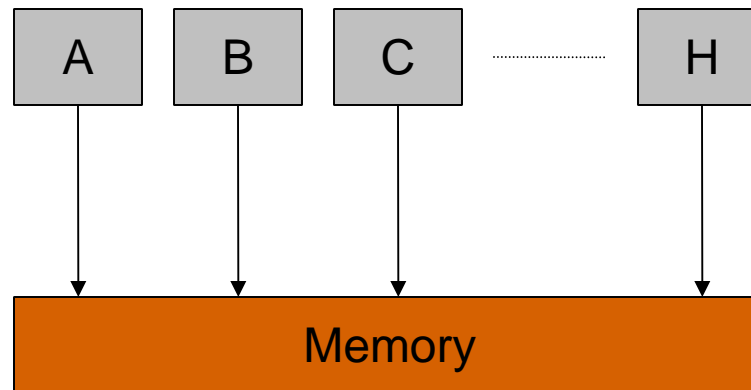


- Increases CPU size, only few special vector commands possible
- Easy to adapt existing code, but not all problems benefit of SIMD parallelism
- Expensive



SMP

- Multiprocessor Supercomputers
- Shared memory
 - Multiple CPUs have access to global memory

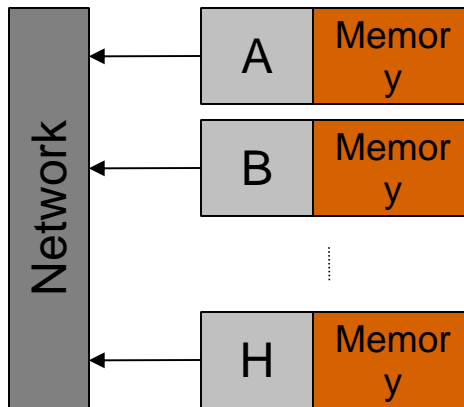


- Problem: Conflicts when accessing the same memory location
- Fast communication, fast memory access, easy to program
- Complex system architecture, limits the number of CPUs



Distributed Memory HPC

- Distributed memory
 - CPUs have local memory

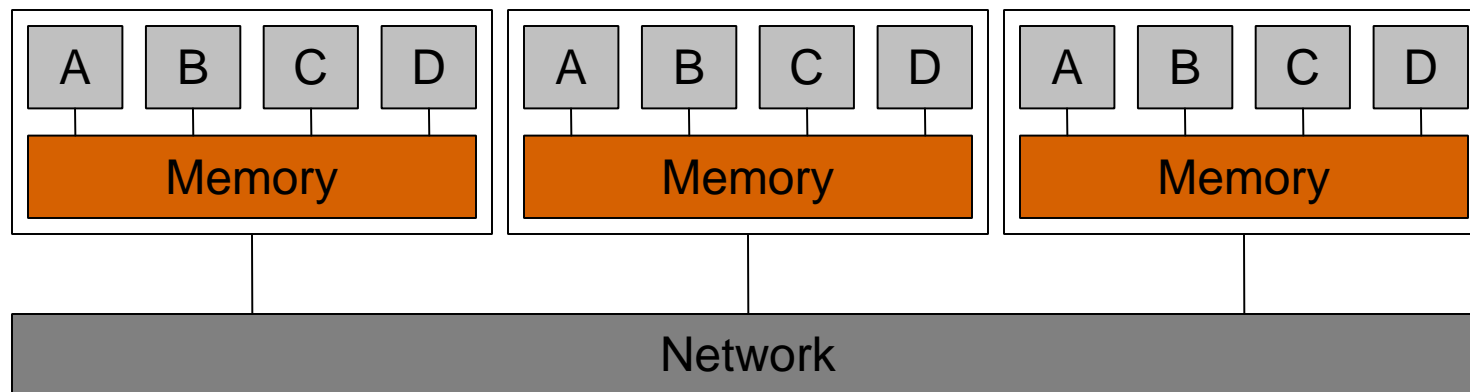


- Parallelization complicated
- Communication bottleneck
- Advantage:
 - Simple system design,
 - Hardware scales very well in respect of number of CPUs (“massive parallel” systems)



High Performance Computing

- Hybrid designs
 - E.g. cluster systems with SMP nodes



- High CPU count and faster communication – but optimization difficult
- Earth Simulator (Japan): 640 nodes
- Nodes: 8 vector processors with shared memory



High Performance Computing

- Research areas / trends in HPC:
 - Unlike earlier a lot of HPCs are built using of-the-shelf-hardware
 - Virginia Tech “Big Mac” (1100 Apple Dual G5)
 - PC cluster systems
 - Problems:
 - Space and power consumption, heat
 - Interconnection networks (bandwidth, latency, cpu overhead)
 - Reliability
 - This made HPC affordable for smaller institutions!
 - Performance analysis
 - Why does a program not scale well?
 - What is the “speed” of a supercomputer?
 - Strategies for problem decomposition
 - Make a parallel code scale better
 - GRID
 - Provide transparent access to supercomputer resources

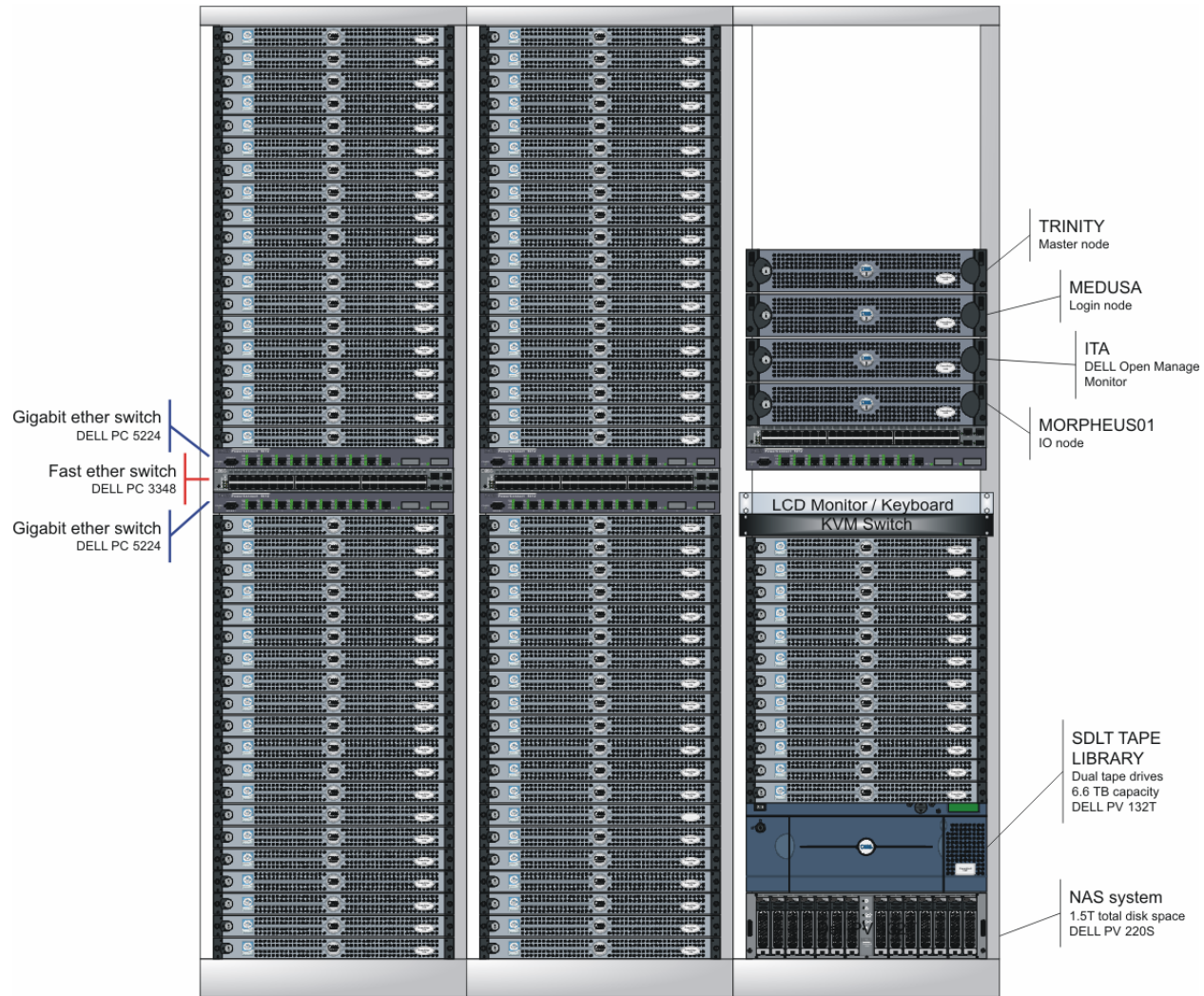


SHIS HPCC

- SHIS Cluster System
 - PC cluster computer with SMP nodes:
 - 90 nodes with 2 Xeon CPUs each (2.8 GHz)
 - CPUs support Hyperthreading
 - 2 GB RAM each node
 - 80 GB HD each node
 - Gigabit ethernet interconnection network
 - 1.5 TB global harddrive space
 - 6.8 TB SDLT tape library
- Performance:
 - 0.59 TFlops
 - 1 TFlops (Peak)



SHIS HPCC



SHIS-HPCC

SHIS HPCC

- Software
 - Linux RedHat 9 Operating System
 - Message Passing Interface - MPI (MPICH¹ and MPIpro²)
 - Portable Batch System – PBSPro³
 - Ganglia Performance Monitor⁴
- SHIS Team
 - HPCC Committee
 - Dr. Jiajie Zhang
 - Support:
 - David Ha

1) <http://www-unix.mcs.anl.gov/mpi/mpich>

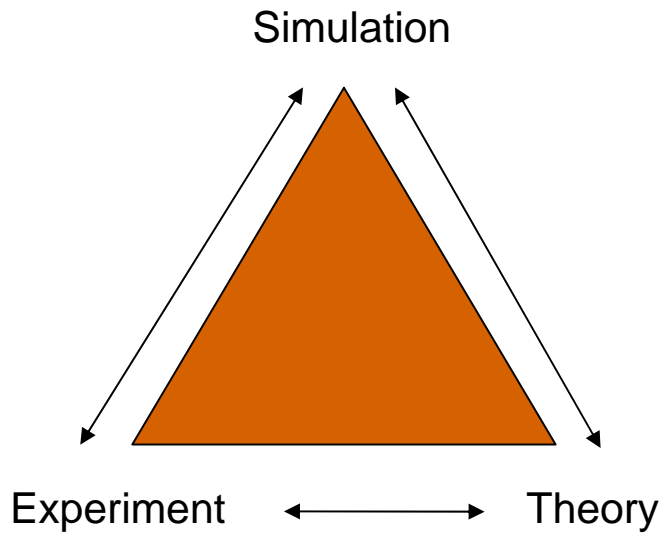
2) <http://www.mpi-softtech.com>

3) <http://www.pbspro.com>

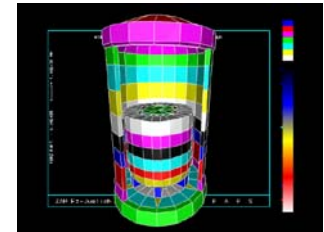
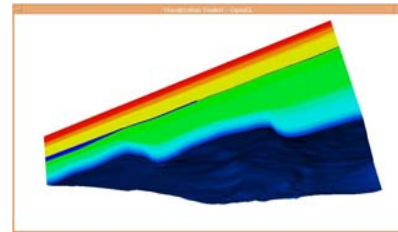
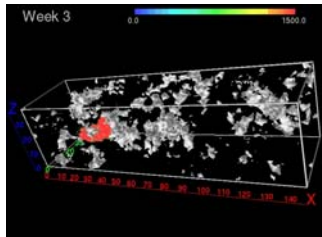
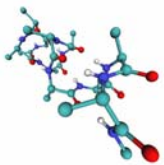
4) <http://ganglia.sourceforge.net>



Applications



- Simulation
 - Biophysics
 - Meteorology
 - Fluid dynamics
 - Finite element calculations
 - Traffic simulations
 - Artificial life



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Applications

- How to develop applications for a supercomputer?
- Automatic parallelization
- Programming languages
 - Fortran, C, C++
 - Interpreted languages problematic (Java, Python, Perl, ...)
 - Optimization
- Programming model depends on architecture
 - MPI (distributed memory)
 - OpenMP (shared memory)



Visualization

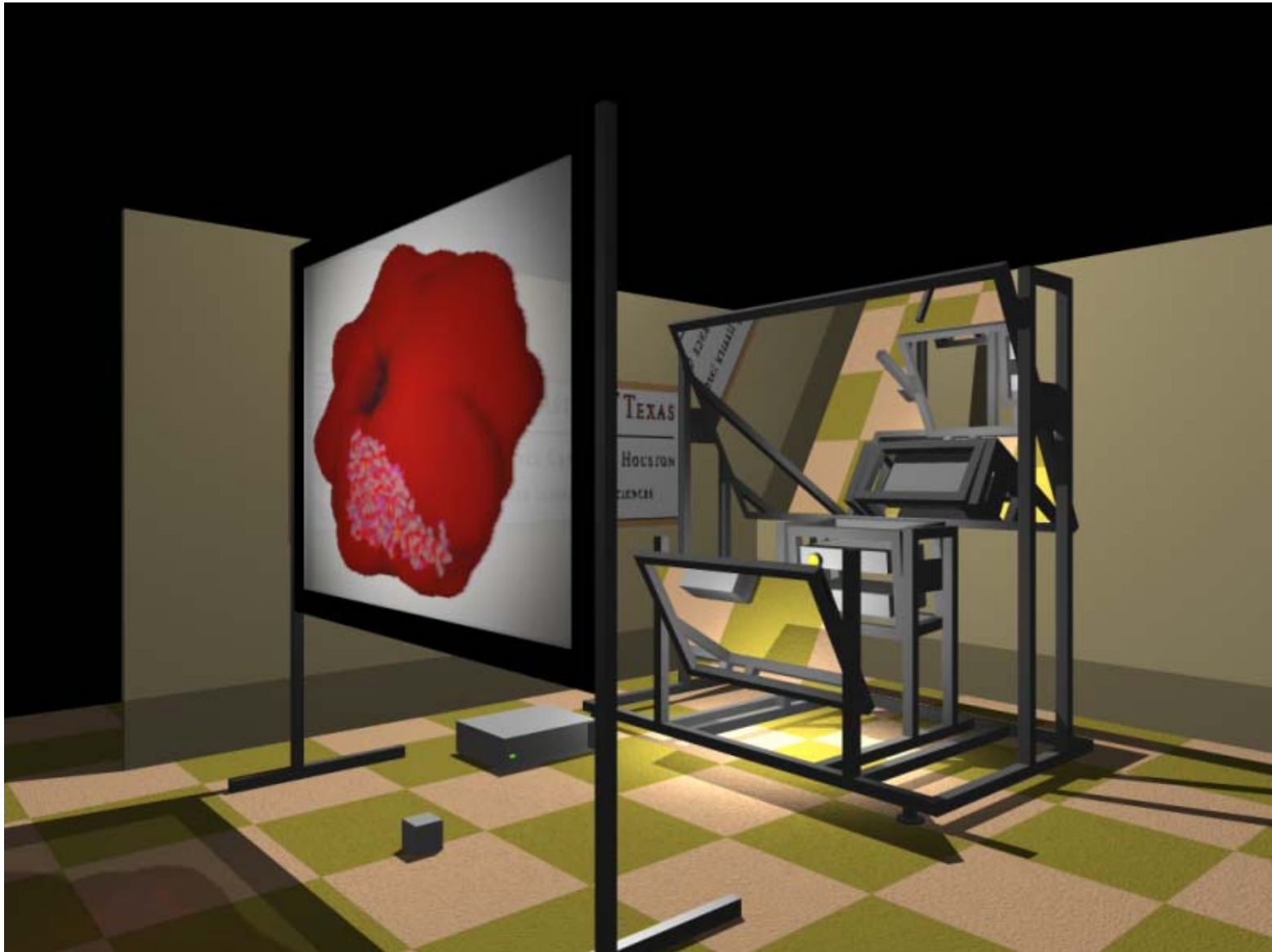
- Visualization essential to analyze data sets from HPC simulations
 - Exploration of datasets
 - Discover
 - Decide
 - Explain
- Online supervision and / or steering of simulations
- Challenges
 - Interactive framerates ~30 FPS
 - Size of datasets is increasing dramatically every year
 - Development of special rendering techniques necessary
 - Network bandwidth limited or latency problems
 - Find useful representations for multidimensional datasets



Virtual Reality

- Goal: Interact with virtual objects like with real objects
- VR systems:





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SHIS VR System

- Components
 - 2 DLP InFocus LP530 projectors
 - Polarization filters for passive stereo
 - Steward (polarization preserving) screen and mirror system
 - Polhemus Fastrak electro-magnetic position tracker
 - 3 standard sensors and 1 stylus-like sensor
 - Computer system
 - Dual Xeon 3 GHz
 - nVidia Quadro FX 2000
 - 2 GB Ram
 - RedHat / Fedora Core Linux
 - Supports OpenGL and passive stereo

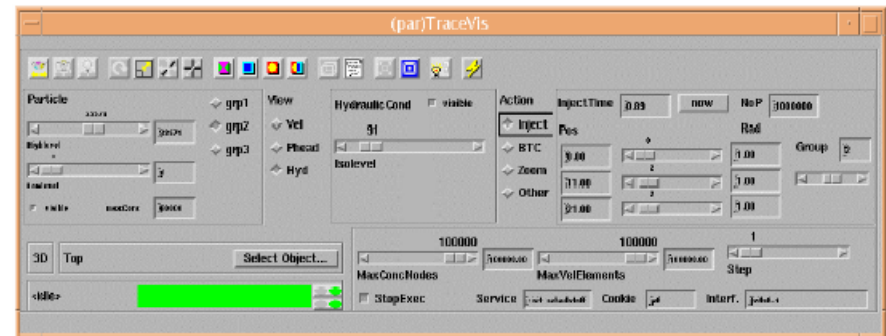
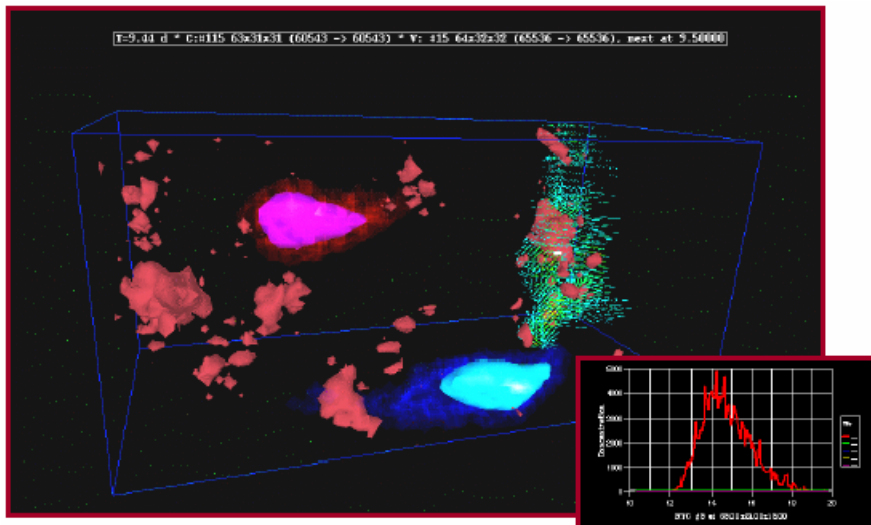


Polhemus Fastrak



Virtual Reality

- Steering of supercomputer applications
 - Solute transport in variable saturated porous media
 - Simulation “TRACE”¹ (environmental research)
 - Online supervision of simulation running on massive parallel HPC with TraceVis²
 - Steering: Injection of solute into simulated area during simulation run



- 1) <http://www.fz-juelich.de/icg/icg4>
- 2) <http://www.fz-juelich.de/zam>



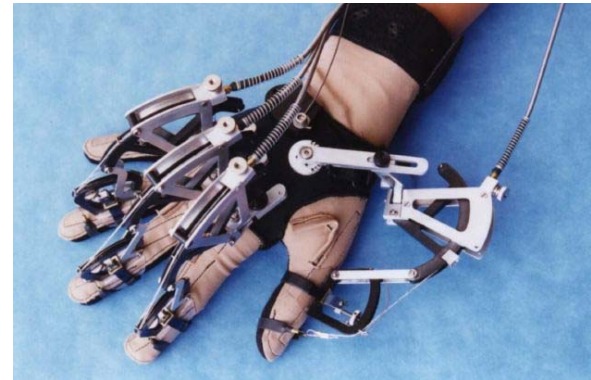
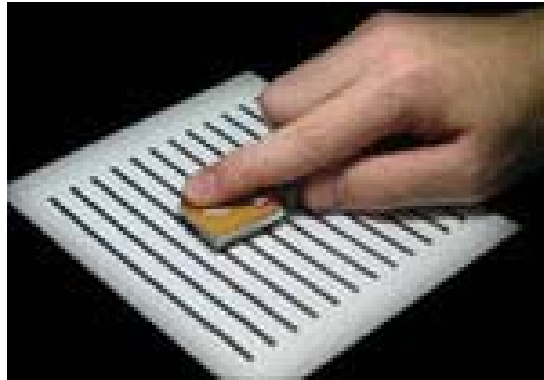
Haptic Rendering

- Haptic Rendering
 - *Haptesthai* – greek “to touch”
 - Create an artificial tactile sensation
- Applications:
 - Experience surface / mass of virtual objects
 - Teleoperation / telerobotics
 - Exploration of multidimensional datasets
- Challenges:
 - Design of haptic devices
 - High temporal bandwidth:
~1000 force updates per second



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Haptic Devices

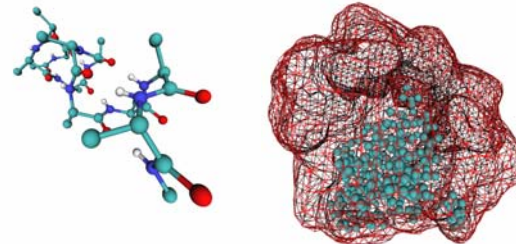
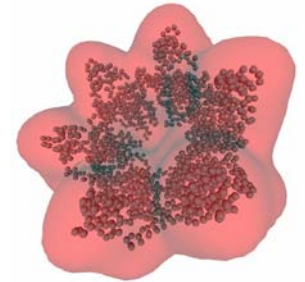


- Sensable Phantom 6DOF
 - Original device developed at the MIT
 - Indirect haptic device
 - Translational forces and torques
 - 6D position / orientation sensors

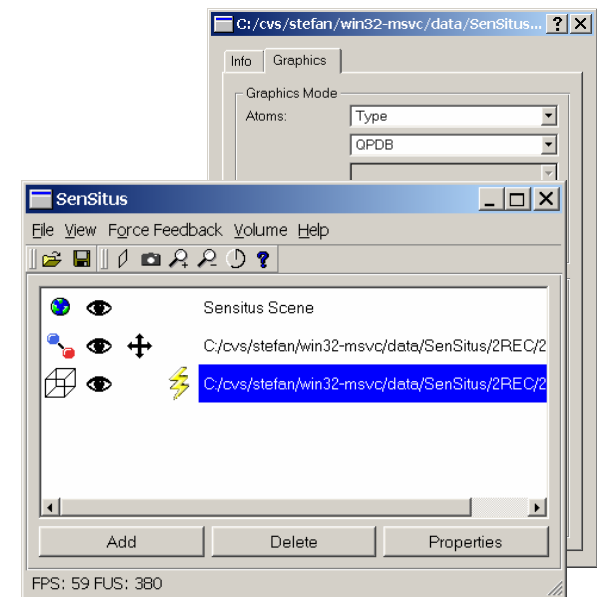


Sculptor

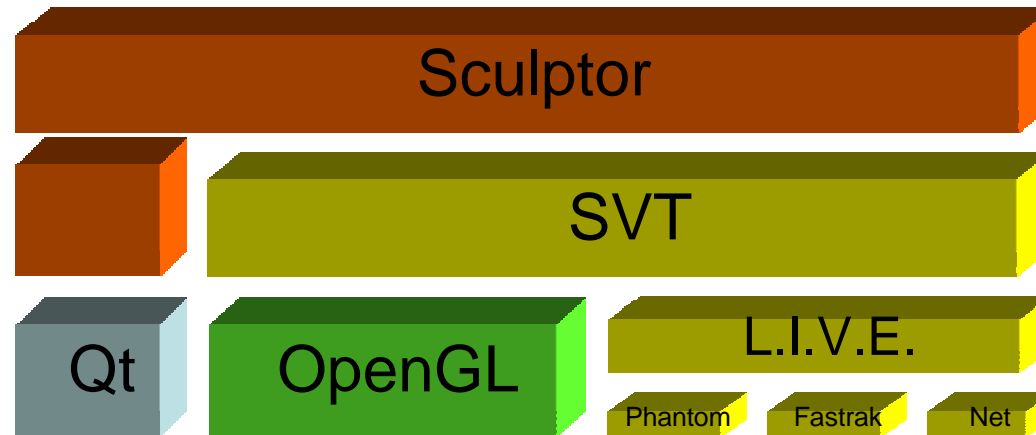
- Sculptor
 - Interactive multiresolution fitting by haptic rendering
 - Visualization of biophysical datasets
 - Support of VR systems
- Research funded by: Human Frontier Science Program
 - UTH/SHIS Laboratories for Biocomputing and Imaging
 - Willy Wriggers (USA)
 - School of Science and Engineering
 - Takeyuki Wakabayashi (Japan)
 - CRNS, Laboratoire de Genetique des Virus
 - Jorge Navaza (France)
 - RCJ, John von Neumann Institute for Computing
 - Herwig Zilken (Germany)



sculptor.biomachina.org



Sculptor

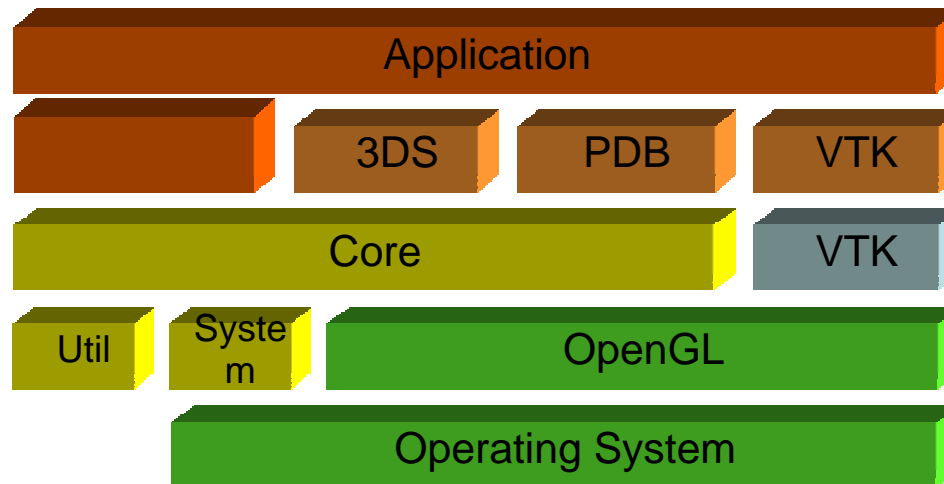


- Sculptor:
 - Qt¹ GUI library
 - OpenGL² 3D graphics library
 - SVT - Underlying VR and visualization toolkit
 - Multiplatform (Linux, SGI, Windows)

1) <http://www.opengl.org>
2) <http://www.trolltech.com>



Sculptor



- SVT:
 - Multi-Display VR environments
 - No dependencies to other libraries
 - Encapsulation of all system dependent calls



Interactive Multi-Resolution Fitting

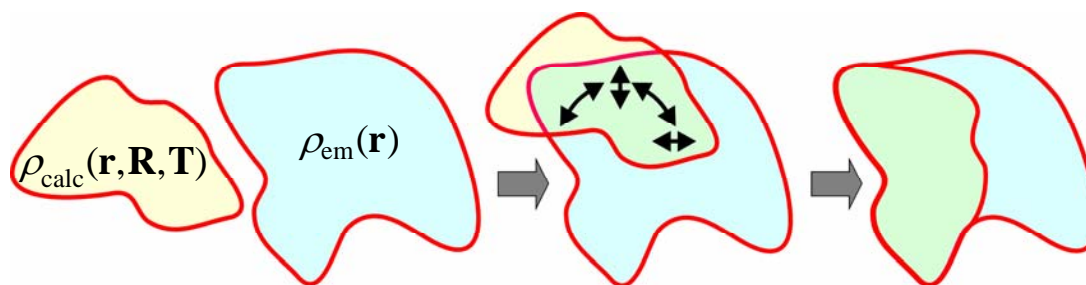
- Fitting of high-resolution crystal structures into low resolution electron density maps
 - High-resolution molecular structures obtained by x-ray crystallography
 - Low-resolution electron microscopy volumetric maps
- New interactive fitting approach using haptic rendering
- Force calculation
 - Gradient of the cross correlation coefficient
 - Guide user to better fitting location



Interactive Multi-Resolution Fitting

- Cross correlation coefficient

$$C(R, T) \propto \int \rho_{calc}(\mathbf{r}, R, T) \cdot \rho_{em}(\mathbf{r}) d^3 \mathbf{r}$$



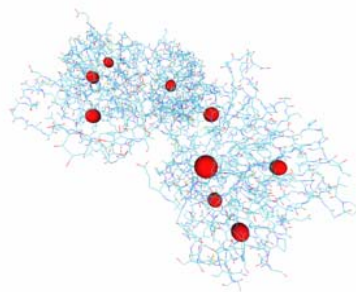
- Problem: Not time efficient enough



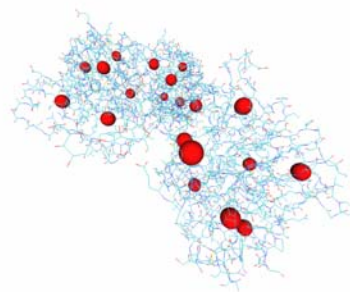
Reduced Fitting Criterion

Vector Quantization

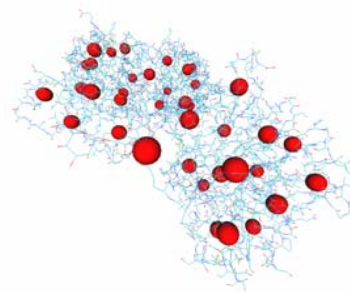
- Vector Quantization
 - Popular method in signal processing
 - Replace complex function by small number of feature vectors
 - Topology Representing Networks (Martinez, Schulten)
- Applied to high-resolution structure to reduce complexity of fitting problem:



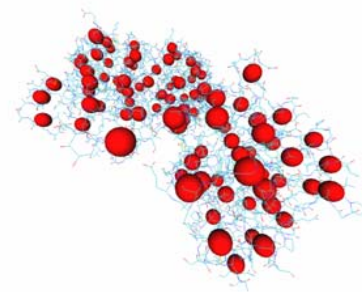
10CV



20CV



40CV



100CV

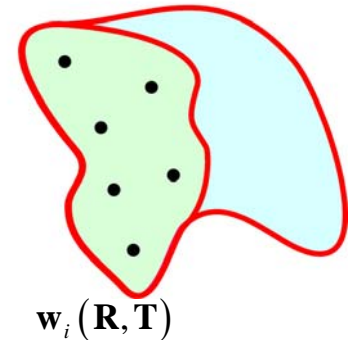


Reduced Fitting Criterion

Cross Correlation

- Replace complex crystal structure by feature vectors

$$\rho_{calc}(\mathbf{r}) \equiv \sum_{i=1}^k \delta(\mathbf{r} - \mathbf{w}_i)$$



- Reduced cross correlation criterion:

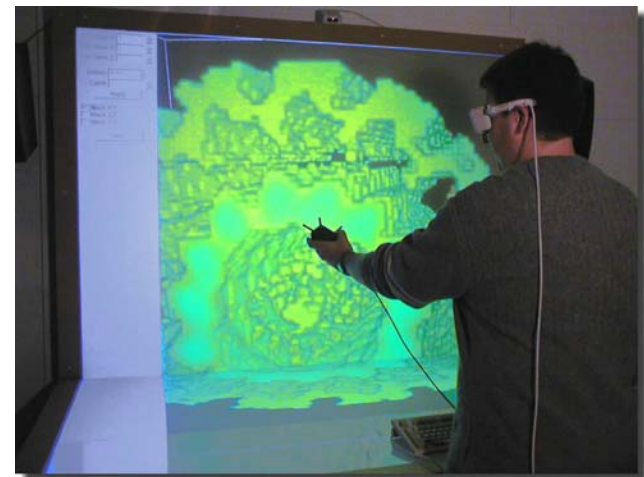
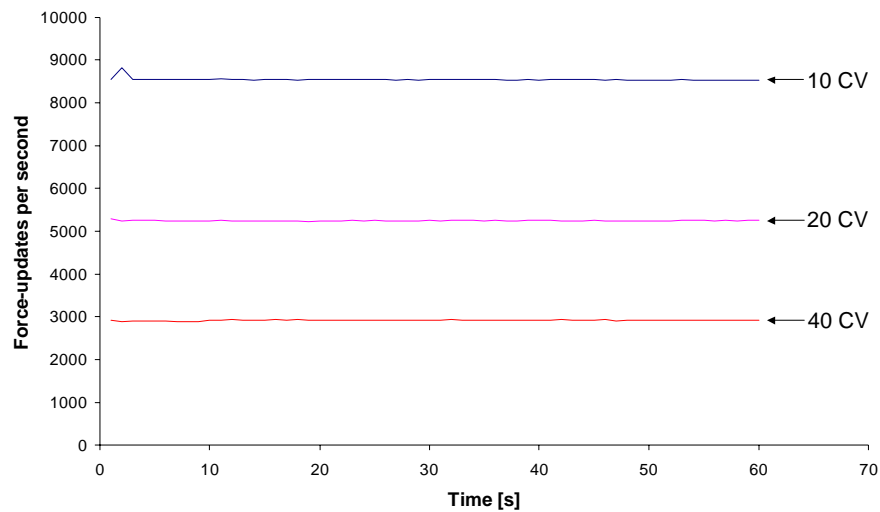
$$C(R, T) \propto \sum_{i=1}^k \rho_{em}(\mathbf{w}_i(R, T))$$

- Reduced criterion is time efficient enough for haptic rendering



Reduced Fitting Criterion Cross Correlation

- By using this reduced fitting criterion we were able to achieve update frequencies $>1\text{KHz}$



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